

MSC711x Packet Telephony Farm Card (SPT711xPFCE)

The MSC711x packet telephony farm card (SPT711xPFCE) accelerates time to market of MSC711x DSP voice over internet protocol (VoIP) designs. This card contains a farm of four StarCore™-based MSC711x DSP devices aggregated through a ten-port Ethernet switch and interfacing with a computer telephony (CT) bus carrying up to four TDM streams. The board meets the common mezzanine card (CMC) specification for a single-width form factor. Two separate CMC connector sites, one on each side, provide the pin connections for two different development platforms.

The board is designed to connect to the Freescale Packet Telephony Development Kit (PDK) and the Freescale Modular Development System (MDS). Both development platforms are designed with Freescale PowerQUICC™ processors. One side has three CMC connectors placed as described in the CMC specification, plus a fourth non-standard CMC connector for additional signalling. The other side has all four standard CMC connectors. All power/ground and most signal connections match the PCI telecom mezzanine card (PTMC) specification (type 3).

The devices can boot standalone through an on-board I²C EEPROM or under external host control through the host processor bus interface. Typical data flow converts VoIP traffic from the Ethernet switch to the TDM bus and generates VoIP traffic using data from the TDM bus.

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Software support and examples for the SPT711xPFCE are available in the PDK. The latest release of the libpdk software for Linux supports the SPT711xPFCE.

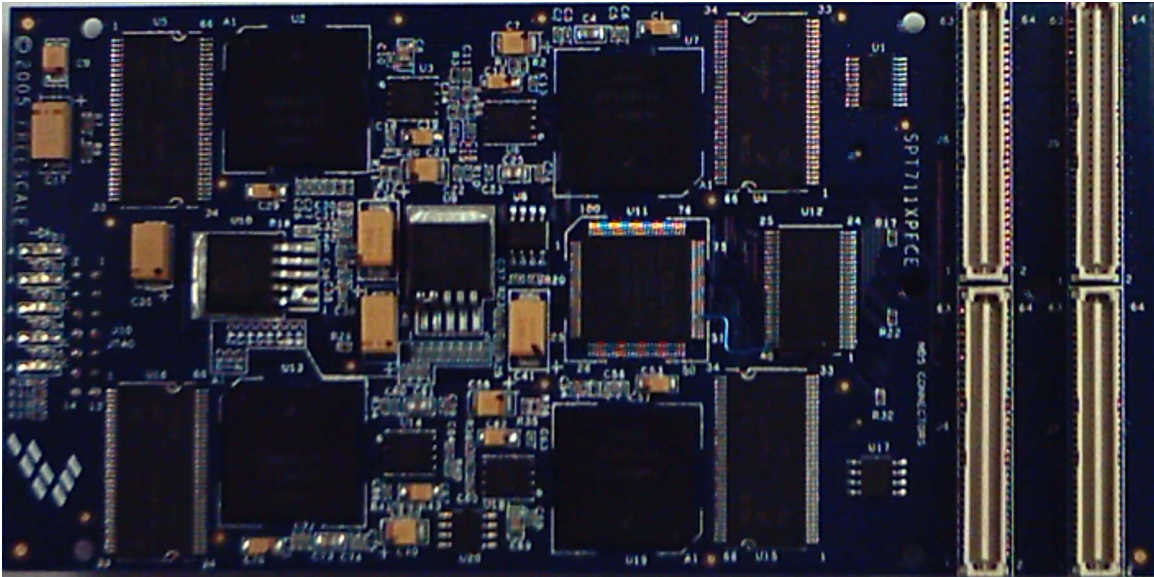


Figure 1. MSC711x Packet Telephony Farm Card (SPT711xPFCE)

Features of the SPT711xPFCE are as follows:

- CMC/PMC form factor.
- Two sets of CMC connector sites:
 - Compatible with the Packet Telephony Development Kit (PDK).
 - Compatible with the PowerQUICC™ modular design system (MDS).
- 4 MSC711x DSP devices running at up to 300 MHz.
- 16 Mbyte of 16-bit double data rate (DDR) SDRAM for each MSC711x DSP device.
- 32 Kbyte of I²C EEPROM for MSC711x boot memory.
- 32 Kbyte of I²C EEPROM for Ethernet switch configuration.
- On-board 10-port Ethernet switch.
- Four TDM streams connected to all MSC711x DSP devices.
- 72 Macrocell complex programmable logic device (CPLD) for I/O and reset control.
- JTAG™ connection for in-system debugging of all MSC711x DSP devices and CPLD.
- CPLD control of boot time mode selection.
- Requires 3.3 VDC and 5 VDC supplied from an external source:
 - 3.3 VDC generates 2.5 VDC for DDR interfaces.
 - 5 VDC generates 1.2 VDC for MSC711X DSP device core voltage.

1 Packet Telephony Development Kit

The *Packet Telephony Development Kit (PDK)* is a Freescale platform for evaluating and developing voice-over packet applications. The PDK has an MPC8260 host network processor that runs Linux, StarCore DSP resource cards that run DSP code, and a public switched telephone network (PSTN) card with interfaces such as E1/T1 and analog telephone lines (see **Figure 2**).

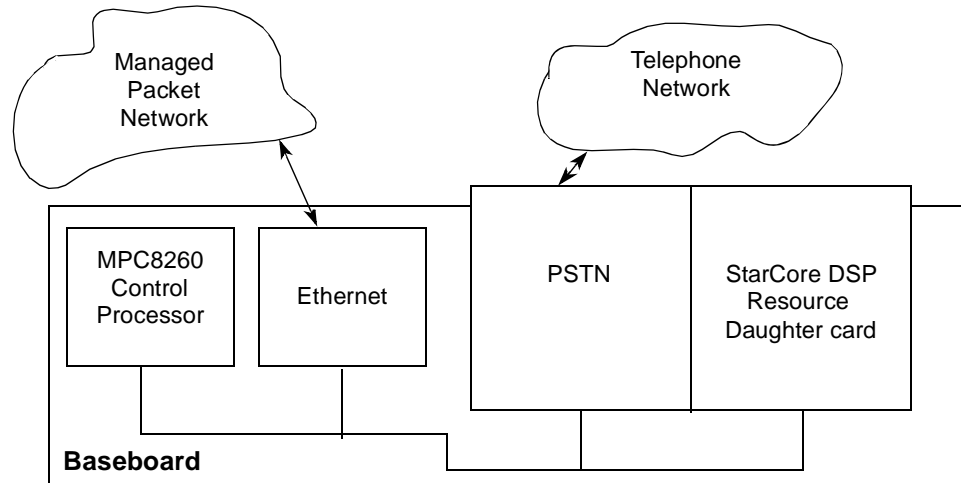


Figure 2. Components of the PDK

The documentation for the kit components is listed in **Table 1**.

Table 1. PTK Components and Their Associated Documents

Component	Document	Document ID
Baseboard	<i>Packet Development Kit Baseboard Hardware User's Guide</i>	PTKITBASEUG
MPC8260 control processor	<i>MPC8260 PowerQUICC II™ Family Reference Manual</i> (Available at the website listed on the back page of this user's guide.)	MPC8260UM
PSTN card	<i>Packet Development Kit PSTN Mezzanine User's Guide</i>	PTKITPSTNUG
StarCore DSP resource daughter card	<ul style="list-style-type: none"> • <i>MSC8102 Packet Telephony Farm Card (MSC8102PFC) User's Guide</i> • <i>MSC8101 Packet Telephony Farm Card (MSC8101PFC) User's Guide</i> • <i>MSC8122 Packet Telephony Farm Card (MSC8122PFC-HV) User's Guide</i> • <i>MSC711x Packet Telephony Farm Card (SPT711xPFCE) User's Guide</i> 	PTKIT8102UG PTKIT8101UG PTKIT8122UG PTKIT711xUG
MSC8122 processor	<i>MSC8122 Reference Manual</i> and other MSC8122 documentation are located at the web site listed on the back cover of this user's guide.	MSC8122RM
MSC8103 processor	<i>MSC8103 Reference Manual</i> and other MSC8103 documentation are located at the web site listed on the back cover of this user's guide.	MSC8103RM
Software	<i>Packet Telephony Development Kit Software User's Guide</i>	PTKITSOFTUG

CAUTION

The packet telephony development kit includes open-construction printed circuit boards that contain static-sensitive components. These boards are subject to damage from electrostatic discharge (ESD). To prevent such damage, you must use static-safe work surfaces and grounding straps, as defined in ANSI/EOS/ESD S6.1 and ANSI/EOS/ESD S4.1. All handling of these boards must be in accordance with ANSI/EAI 625.

Table 2. Reference Documents

Document	Revision	Date	Document ID
Standard Physical and Environmental layers for PCI Mezzanine Cards: PMC	Draft 2.4	January 12, 2001	IEEE: P1386.1
Standard for a Common Mezzanine Card Family: CMC	Draft 2.4a	March 21, 2001	IEEE: P1386
CompactPCI PCI Telecom Mezzanine Card Specification	R1.0	April 11, 2001	PICMG 2.15
H.100 Hardware Compatibility Specification: CT Bus	1.0		H.100

2 System Interfaces

To support VoIP applications development, the SPT711xPFCE provides four time-division multiplex (TDM) and four Ethernet interfaces at the CMC connectors (see **Figure 3**). It includes interfaces for program storage, download, and debug. These interfaces can also be used to transfer control messages with a system controller.

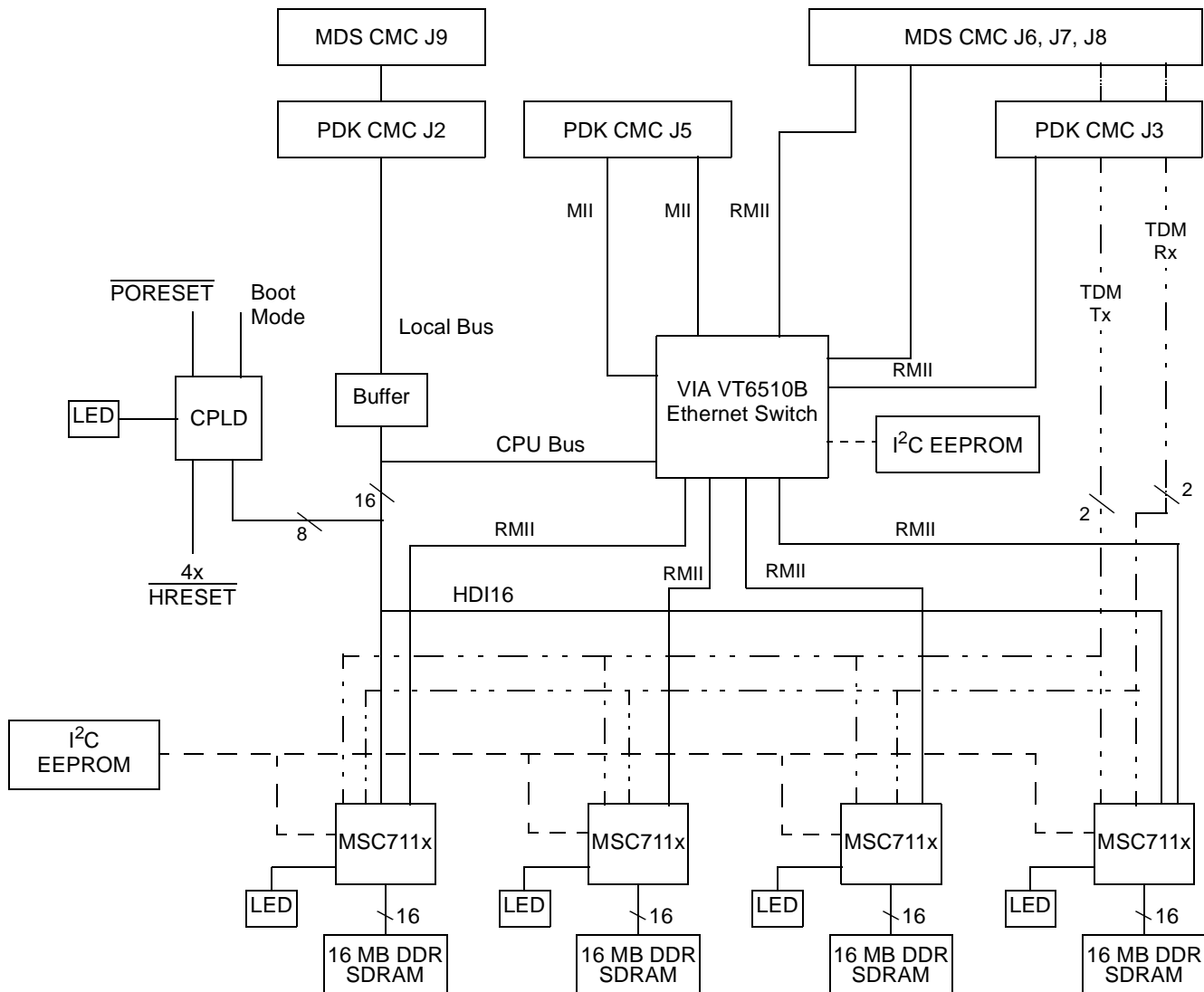


Figure 3. Block Diagram of SPT711xPFCE

2.1 External Bus Through Programmable Logic

A complex programmable logic device (CPLD) converts bus transfers on the CMC connectors to HDI16, Ethernet switch, or CPLD register transfers. This logic decodes the address and asserts the proper chip-select signal when the PFC chip-select signal is asserted. The host device must meet the timing requirements for the MSC711x HDI16, Ethernet switch, and CPLD register transfers, assuming a 10 ns delay through the CPLD. **Figure 4** shows the timing requirements for the Ethernet switch, which is the slowest interface and therefore the driving influence on timing considerations. The actual value of timing requirements is implementation-specific. Review all device specifications to determine the values.

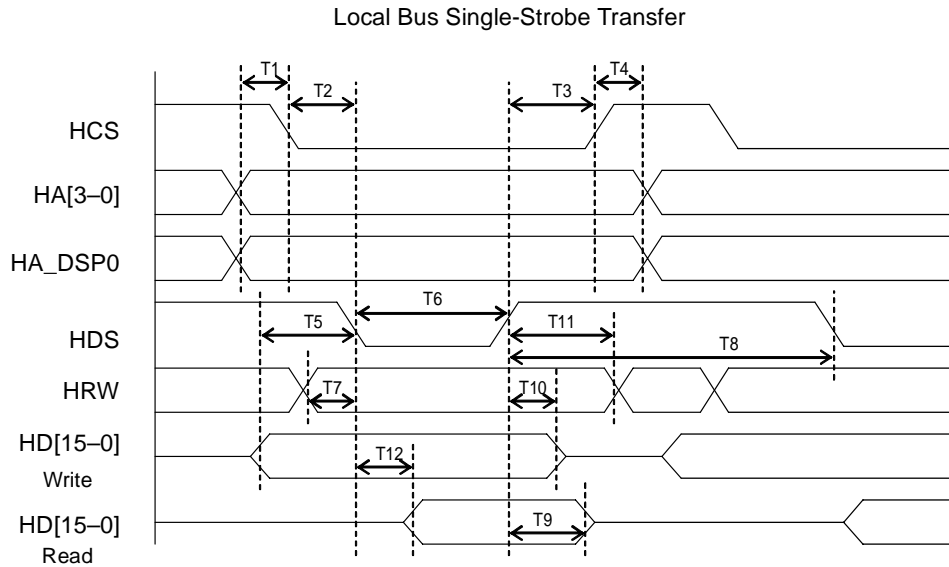


Figure 4. Bus Transfer Timing Diagram

The CPLD contains registers for controlling and/or sampling several board signals. These signals include reset, power and LED control, and interrupts. Consult **Section 7, CPLD Registers**, on page 25 and the board schematics for information on signals controlled or sampled by the CPLD registers.

Table 3. Bus Transfer Timing Intervals

Description	Key	Minimum
Address set-up before the chip select	T1	10 ns
Chip-select set-up before the data strobe	T2	10 ns
Chip-select hold after the data strobe	T3	10 ns
Address hold after the chip select	T4	0 ns
Write data set-up before the data strobe assertion	T5	10 ns
Data strobe width	T6	40 ns
HRW set-up before the data strobe	T7	10 ns
Data strobe after the data strobe	T8	20 ns
Read data hold after the data strobe deassertion	T9	10 ns
Write data hold after the data strobe deassertion	T10	5 ns
HRW hold after the data strobe	T11	10 ns
Read data valid after the data strobe assertion	T12	30 ns

2.2 Ethernet (MII/RMII)

Two media-independent interfaces (MII) and three reduced MII (RMII) are available for connection to an external host board at the CMC connectors. All four MSC711x devices connect to separate full duplex RMII ports of the on-board ten-port Ethernet switch. One full duplex RMII port from the switch connects to J3 of the PDK CMC site. Two full duplex RMII ports for the switch connect to J8 of the MDS CMC site. **Figure 5** shows a diagram of the Ethernet switch port connections on the board. The switch is configured through its CPU bus interface (see **Figure 3**).

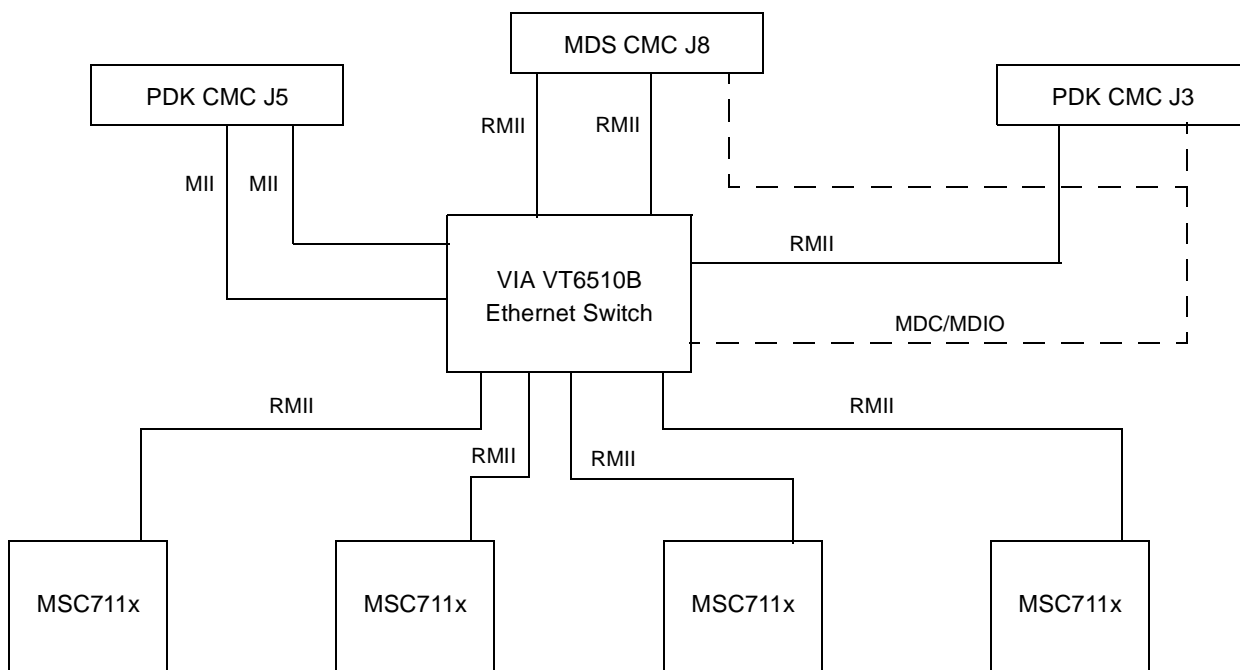


Figure 5. Ethernet Connections

Table 4. VIA Ethernet Switch Port Connections

Port	Type	Connection
0	RMII	MSC711x Device 0
1	RMII	MSC711x Device 1
2	RMII	MSC711x Device 2
3	RMII	MSC711x Device 3
4	RMII	MDS CMC
5	RMII	MDS CMC P3
6	RMII	PDK CMC
7	RMII	No Connection
8	MII	PDK CMC P5
9	MII	PDK CMC P5

2.3 Time-Division Multiplex (TDM) Bus

Four streams of TDM data are available for connection to an external host board and are connected to all MSC711x DSP devices. The streams connect to J3 of the PDK CMC site and J6, J7, and J8 of the MDS CMC site. One pair of frame and clock signalling is provided for all TDM streams. Streams CT_D1 and CT_D5 must be used for TDM streams from the external host to the DSP farm. Streams CT_D0 and CT_D4 must be used for TDM streams from the DSP farm to the external host. The frame and clock signals are buffered and then connected to each DSP device. The CT_D0, CT_D1, CT_D5, and CT_D4 signals are connected directly from the DSP devices to the CMC connectors. **Figure 6** shows the TDM stream connections on the board.

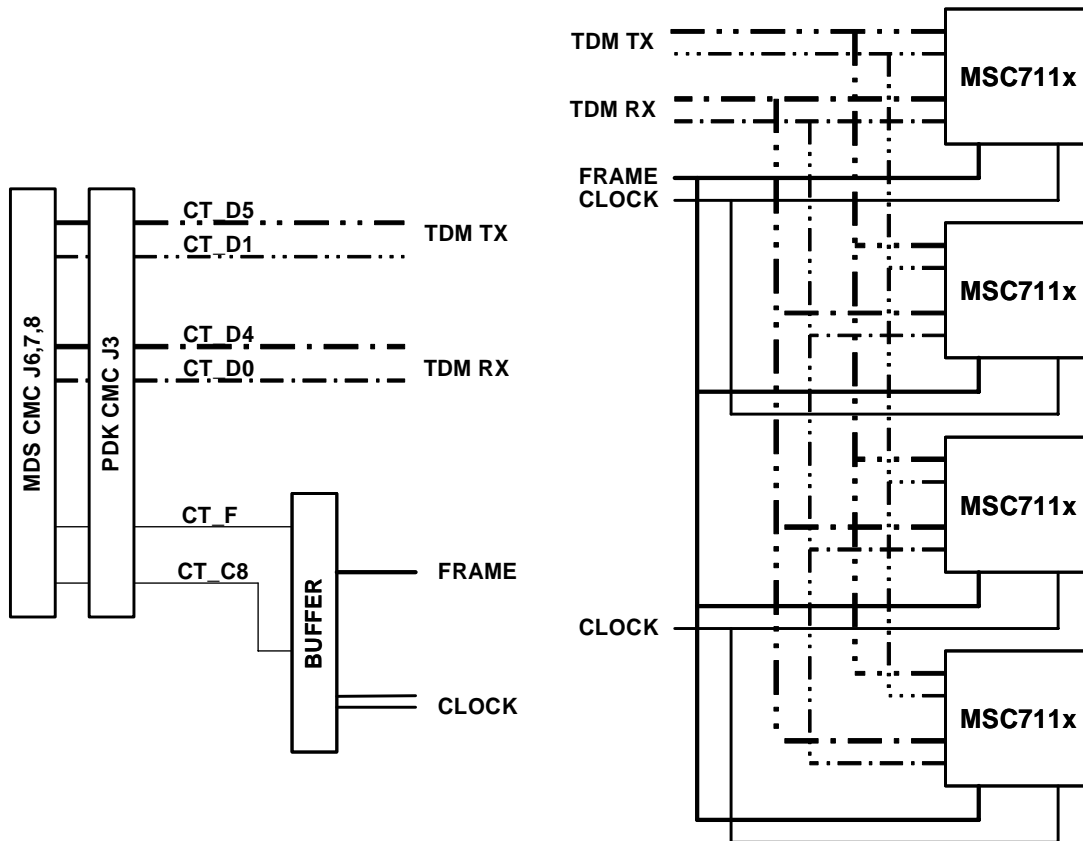
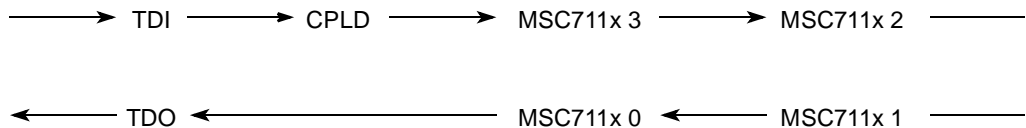


Figure 6. TDM Connections

2.4 JTAG Connector

Connector J10 is a 14-pin 0.100 inch pitch header that provides JTAG debugger access to the board. For details on the connector signals, refer to the schematics in [Appendix A](#). One JTAG chain on the board connects all four MSC711x devices and the CPLD. The chain is connected as follows:



3 Hardware

Figure 7 depicts the main components of the SPT711xPFCE board, which are the MSC711x DSP devices, CPLD, Ethernet switch, I²C bus devices, and voltage regulators.

3.1 MSC711x DSPs

The MSC711x family of highly integrated DSPs targets high-bandwidth computationally intensive DSP applications and is optimized for Enterprise class packet telephony applications. These processors deliver enhanced performance while maintaining low power dissipation and greatly reducing system cost.

At the heart of an MSC711x DSP device is the StarCore™ SC1400 core, providing the processing power for intensive numeric processing. The four ALUs in the SC1400 core work together to deliver 800 million multiply and add commands per second (MMACS) performance with an internal 200 MHz clock at 1.2 V. An extended core services the SC1400 bandwidth requirements, with high speed zero wait state memory elements for both program and data accesses. In the extended core are a multi-ported 64 or 192 Kbyte level 1 internal memory (M1) for both high speed program and data storage. A 16 Kbyte, 16-way instruction cache (ICache) provides an instruction stream to the core with no wait states on cache hits. The efficiency of the ICache is greatly enhanced by an intelligent fetch unit with advanced features for real-time processing. A 4-entry write buffer allows the SC1400 core to continue processing while the write buffer writes to locations outside the platform. A 192 Kbyte level 2 memory (M2) is also available on some MSC711x family devices for bursting to the ICache and for accesses from the extended core.

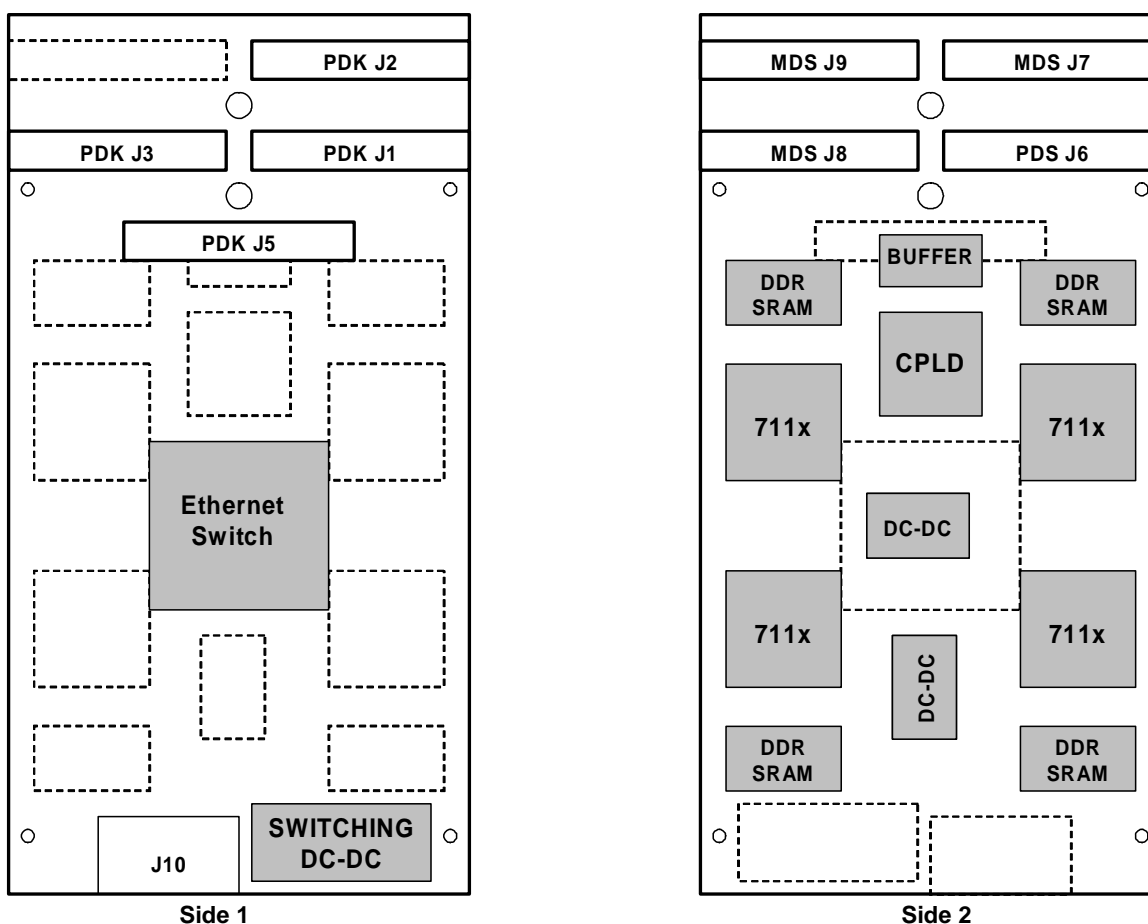


Figure 7. Major Components of the SPT711xPFCE

Each device in the MSC711x family is designed for optimal data flow to/from the SC1400 core. Wide full-speed buses exactly match the busing requirements of the SC1400 core. Data is transferred to the DSP from either the external memory interface, the Ethernet controller on some devices, the host interface, or the TDM serial interfaces. The flexible DMA controller transfers data through the bus switch from any of these ports to buffers in the internal memories. The SC1400 cores and other modules interconnect via a crossbar switch that manages rapid data transfer and storage between the MSC711x device, its internal components, and external devices. This multi-port crossbar switch allows multiple data transfers to occur

in parallel outside the extended core. The SC1400 core processes the data in the buffers and the result is transferred back to one of the ports. **Figure 8** shows a block diagram of the MSC7116 device. Unlike some devices in the MSC711x family, the MSC7116 has an Ethernet port.

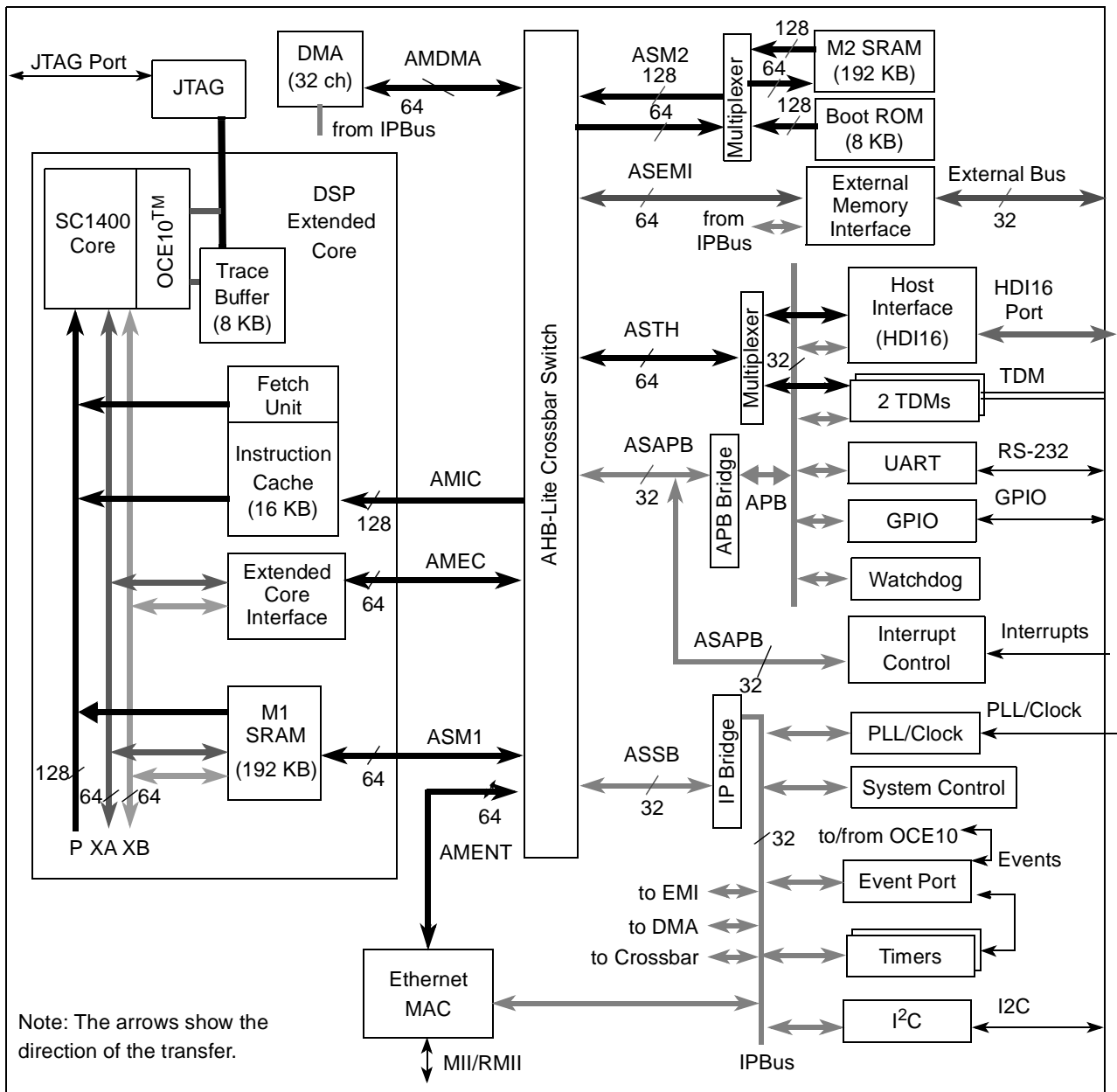


Figure 8. MSC7116 Block Diagram.

The flexible 32-channel DMA controller transfers data to and from internal memory, external memory, peripherals, the host data interface, and the TDM interfaces. The DDR-RAM memory controller enables the SC1400 cores to access external memory devices with glueless accesses to DDR-RAM memory devices on the system bus. For more information on the MSC711x family of DSP devices, visit the Freescale Semiconductor web site listed on the back cover of this document.

3.2 DDR SDRAM

Each MSC711x device has a dedicated 16-bit (DDR synchronous dynamic random access memory (SDRAM) device for external memory storage. These devices provide 16 Mbyte of external memory to each device. The memory devices connect to the dedicated DDR SDRAM interface on each MSC711x device. [Example 1](#) shows the basic initialization code for the Micron DDR SDRAM memory as connected on the SPT711xPFCE. These devices are Micron part number MT46V8M16P-6T. For information on these devices, refer to the Micron web site at [http:// www.micron.com](http://www.micron.com).

Example 1. Micron DDR Initialization Code

```
typedef struct
{
    unsigned int UP;
    unsigned int START;
    unsigned int BYTES;
    unsigned int WIDTH32;
    unsigned int CS0CFG;
    unsigned int TCFG1;
    unsigned int TCFG2;
    unsigned int SMCFG;
    unsigned int SICFG;
    unsigned int SCFG;
} t_DDR_PARAMETERS;

t_DDR_PARAMETERS DDR_PARAMETERS;

#define DDR_DEFAULT_UP 0
#define DDR_DEFAULT_START 0x20000000
#define DDR_DEFAULT_BYTES 0x01000000
#define DDR_DEFAULT_32BIT 0
#define DDR_DEFAULT_CS0CFG 0x80000001
#define DDR_DEFAULT_TCFG1 0x38345331
#define DDR_DEFAULT_TCFG2 0x00000400
#define DDR_DEFAULT_SMCFG 0x10000062
#define DDR_DEFAULT_SICFG 0x0490007F
#define DDR_DEFAULT_SCFG 0x42000000

// Initialize Global Variables
DDR_PARAMETERS.UP = DDR_DEFAULT_UP;
DDR_PARAMETERS.START = DDR_DEFAULT_START;
DDR_PARAMETERS.BYTES = DDR_DEFAULT_BYTES;
DDR_PARAMETERS.WIDTH32 = DDR_DEFAULT_32BIT;
DDR_PARAMETERS.CS0CFG = DDR_DEFAULT_CS0CFG;
DDR_PARAMETERS.TCFG1 = DDR_DEFAULT_TCFG1;
DDR_PARAMETERS.TCFG2 = DDR_DEFAULT_TCFG2;
DDR_PARAMETERS.SMCFG = DDR_DEFAULT_SMCFG;
DDR_PARAMETERS.SICFG = DDR_DEFAULT_SICFG;
DDR_PARAMETERS.SCFG = DDR_DEFAULT_SCFG;

#if (DDR_DEFAULT_UP)
    // Default is up, so insert the code to bring it up.
    DDR_UP(&DDR_PARAMETERS);
#endif
```

Hardware

```
void DDR_UP(t_DDR_PARAMETERS* params)
{
    unsigned int end;
    volatile ddr_memc_map_t* ddr = (volatile ddr_memc_map_t*) DDR_BASE;
    volatile clk_map_t* clk = (volatile clk_map_t*) CLK_BASE;
    volatile btm_map_t* btm = (volatile btm_map_t*) BTM_BASE;

    // STOPCTL - enable DDR clk
    clk->STOPCTRL &= ~0x00003000;

    // DEVCFG
    if (params->WIDTH32 == 1)
    { btm->CHPCFG |= 0x00000020; } // 32-bit DDR
    else
    {
        // 16-bit
        btm->CHPCFG &= ~0x00000020;

        if (btm->CHPCFG & 0x00000020) // Cannot be cleared
        { params->WIDTH32 = 1; }
    }

    // CSBR0
    end = (params->START) + (params->BYTES - 1);
    if (params->WIDTH32 == 1)
    { ddr->CS0_BNDS = (params->START >> 7) | (end >> 23); }
    else
    { ddr->CS0_BNDS = (params->START >> 6) | (end >> 22); }

    // CS0CFG
    ddr->CS0_CONFIG = params->CS0CFG;

    // TCFG1
    ddr->TIMING_CFG_1 = params->TCFG1;

    // TCFG2
    ddr->TIMING_CFG_2 = params->TCFG2;

    // SCFG (First Time)
    ddr->DDR_SDRAM_CFG = (params->SCFG);

    // SMCFG
    ddr->DDR_SDRAM_MODE = params->SMCFG;

    // SICFG
    ddr->DDR_SDRAM_INTERVAL = params->SICFG;

    // SCFG (Last Time)
    ddr->DDR_SDRAM_CFG = (params->SCFG) | 0x80000000;

    return;
}
```

3.3 Complex Programmable Logic Device (CPLD)

A Xilinx XC9572XL CPLD device implements chip-select logic and logic registers on the SPT711xPFCE board. This device contains 72 macrocells and is programmed through JTAG signals on J10. The CPLD self configures when reset is deasserted and does not require external configuration memory. For information on this device, refer to the Xilinx web site (<http://www.xilinx.com>).

3.4 VIA VT6510B Ethernet Switch

The SPT711xPFCE has an on-board 10 port (2 × MII, 8 × RMI) Ethernet switch connected to both CMC sites and all four DSP devices. The Ethernet switch is a VIA VT6510B (<http://www.vntek.com>).

Example 1 provides basic initialization code for the switch through a host controller connected to the CPLD host interface and using the memory map described in **Section 6**, *CPLD Memory Map*, on page 24.

Code Listing 1. VIA Switch Initialization Code

```

/*****
 * PFC Ethernet Switch Initialization Routines
 *
 *****/
void writeSwitchReg(unsigned int _addr, unsigned char _data)
{
    *pdk_bd_regs.u711xpfc.sw_addr_l = (unsigned short)(_addr%256);
    *pdk_bd_regs.u711xpfc.sw_addr_h = (unsigned short)(_addr/256);
    *pdk_bd_regs.u711xpfc.sw_reg_data = (unsigned short)(_data);
    pdk_waste_clks_10(1000);
}

unsigned char readSwitchReg(unsigned int _addr)
{
    unsigned char readData = 0;
    *pdk_bd_regs.u711xpfc.sw_addr_l = (unsigned short)(_addr%256);
    *pdk_bd_regs.u711xpfc.sw_addr_h = (unsigned short)(_addr/256);
    readData = (unsigned char) *pdk_bd_regs.u711xpfc.sw_reg_data;
    pdk_waste_clks_10(1000);
    return readData;
}

void enableSwitchPhyAutoPolling()
{
    while ((readSwitchReg(0x0405) & 1) != 0);
    writeSwitchReg(0x0404, 0x08); // Enable Auto Polling;
    while ((readSwitchReg(0x0405) & 1) != 0);
}

void disableSwitchPhyAutoPolling()
{
    while ((readSwitchReg(0x0405) & 1) != 0);
    writeSwitchReg(0x0404, 0x04); // Disable Auto Polling;
    while ((readSwitchReg(0x0405) & 1) != 0);
}

// _addr = {4-bit-port-num, 3'b000, 5-bit-reg-num}
void writeSwitchPhy(unsigned short _addr, unsigned short _data)
{
    // Note - Autopolling mode must be disabled
    while ((readSwitchReg(0x0405) & 1) != 0);
    writeSwitchReg(0x0400, (unsigned char)((_addr >> 8) & 0x000f));
    writeSwitchReg(0x0401, (unsigned char)(_addr & 0x1f));
    writeSwitchReg(0x0402, (unsigned char)(_data%256));
    writeSwitchReg(0x0403, (unsigned char)(_data/256));
    writeSwitchReg(0x0404, 0x01); // Write to Phy;
}

```

Hardware

```
    while ((readSwitchReg(0x0405) & 1) != 0);
}

unsigned short readSwitchPhy(unsigned short _addr)
{
    unsigned short rtn;
    unsigned char vals[2];
    // Note - Autopolling mode must be disabled
    while ((readSwitchReg(0x0405) & 1) != 0);
    writeSwitchReg(0x0400, (unsigned char)((_addr >> 8) & 0x000f));
    writeSwitchReg(0x0401, (unsigned char)(_addr & 0x1f));
    writeSwitchReg(0x0404, 0x02); // Read from Phy;
    while ((readSwitchReg(0x0405) & 1) != 0);
    vals[0] = readSwitchReg(0x0402);
    vals[1] = readSwitchReg(0x0403);
    rtn = (unsigned short) vals[0];
    rtn += (((unsigned short) vals[1]) << 8);
    return rtn;
}

int configVIAEthernetSwitch(void)
{
    // Reset Switch (will PORESET dsps due to "strapping pins" shared)
    *pdk_bd_regs.u711xpf.cpld_gcr |= 0x0200;
    pdk_waste_clks_10(100000);
    *pdk_bd_regs.u711xpf.cpld_gcr &= ~0x0200;
    pdk_waste_clks_10(100000);

    // Confirm Communication with Switch
    // Check default MAC for Switch
    if (readSwitchReg(0x0619) != 0x00) { return 1; }
    if (readSwitchReg(0x061a) != 0x40) { return 1; }
    if (readSwitchReg(0x061b) != 0x63) { return 1; }
    if (readSwitchReg(0x061c) != 0x80) { return 1; }
    if (readSwitchReg(0x061d) != 0x00) { return 1; }
    if (readSwitchReg(0x061e) != 0x00) { return 1; }

    // port configuration:
    // 100Mbps, Full Duplex, Output and Input Enabled: 0x03
    // Phy addresses are 0 and 1
    writeSwitchReg(0x0418, 0x00);
    writeSwitchReg(0x0419, 0x01);
    writeSwitchReg(0x0420, 0x03);
    if (readSwitchReg(0x0419) != 0x01) { return 1; } // Check write success
    writeSwitchReg(0x0421, 0x03);
    writeSwitchReg(0x0422, 0x03);
    writeSwitchReg(0x0423, 0x03);
    writeSwitchReg(0x0424, 0x03);
    writeSwitchReg(0x0425, 0x03);
    writeSwitchReg(0x0426, 0x03);
    writeSwitchReg(0x0427, 0x03);
    writeSwitchReg(0x0428, 0x03);
    writeSwitchReg(0x0429, 0x03);
    // PDK Phy Auto-Negotiation
```

```

disableSwitchPhyAutoPolling();
if (readSwitchPhy(0x0802) == 0x0013)
{
    writeSwitchPhy(0x0800, 0x8000);
    while ((readSwitchPhy(0x0800) & 0x8000) != 0);
    writeSwitchPhy(0x0804, 0x0DE1); // Capabilities
    writeSwitchPhy(0x0800, 0x1000); // Enable Auto-Negotiation
    if (readSwitchPhy(0x0804) != 0x0DE1)
    { return 1; }
}
if (readSwitchPhy(0x0902) == 0x0013)
{
    writeSwitchPhy(0x0900, 0x8000);
    while ((readSwitchPhy(0x0900) & 0x8000) != 0);
    writeSwitchPhy(0x0904, 0x0DE1); // Capabilities
    writeSwitchPhy(0x0900, 0x1000); // Enable Auto-Negotiation
    if (readSwitchPhy(0x0904) != 0x0DE1)
    { return 1; }
}

return 0;
}

```

3.5 I²C Bus Devices

There are two I²C EEPROM devices on the SPT711XPFCFCE. One connects only to the VIA Ethernet switch, and the other connects to all four MSC711x devices. The I²C address for the EEPROM connected to the switch is 0b1010001x. The I²C address for the EEPROM connected to MSC711x devices is 0b1010000x. The EEPROM devices are part number M24256-BWMN6G from ST Microelectronics. For more information, refer to the manufacturer website (<http://www.st.com>).

Example 2 shows how to initialize the interface, write a test pattern to the EEPROM at address 0b1010000x, read the test pattern back, and then erase the EEPROM. To use this code to test the I²C interface, simply write the test pattern using one of the four MSC711x devices and then read the test pattern back from all four devices. Finally, use one of the four devices to erase the test pattern.

Example 2. I²C EEPROM Access Example Code for MSC711x Devices

```

#define I2C_BUF_SIZE 1024
unsigned char I2C_BUFFER[I2C_BUF_SIZE];

/*****
I2C_UP()
Initialize I2C Interface - no interrupts, polling only, master only
ARGS:
    d_addr      : 7-bit address of this device
RTNS:
    0 = Success
    1 = Failure
*****/

int I2C_UP(unsigned char d_addr)
{
    gpio_map_t *pstGPIO = (gpio_map_t *)GPIO_BASE;
    i2c_map_t* I2C = (i2c_map_t*) I2C_BASE;

```

Hardware

```
// Configure Pins
pstGPIO->gp[0].GP_CTL |= 0x0000C000;

// Disable Control Register
I2C->I2CR = 0x00;

// Set slowest I2C bus speed possible
I2C->IFDR = 0x3f;

// Set address
I2C->IADR = (d_addr << 1) | 0x08;

// Enable Control Register
I2C->I2CR = 0x80;

return 0;
}

/*****

I2C_STATUS()
Check if I2C is initialized
ARGS:
    (None.)
RTNS:
    0 = Down
    1 = Up
*****/

int I2C_STATUS()
{
    i2c_map_t* I2C = (i2c_map_t*) I2C_BASE;

    if (I2C->I2CR & 0x80)
    { return 1; }

    return 0;
}

/*****

I2C_RX()
Receive number of bytes from the bus.
ARGS:
    *data      : Data buffer for received
    cnt        : Number of bytes to read
RTNS:
    Number of bytes received successfully.
*****/

int I2C_RX(unsigned char *data, int cnt)
{
    i2c_map_t* I2C = (i2c_map_t*) I2C_BASE;
    int x = 0;

    // Receive mode
    I2C->I2CR &= ~0x0010;

    // Set or clear Ack control before dummy read
    if (cnt > 1)
    { I2C->I2CR &= ~0x0008; }
    else
    { I2C->I2CR |= 0x0008; }
```



```

// Read data (dummy read to start transfer)
data[x] = (unsigned char) I2C->I2DR;
cnt--;

while (cnt > 0)
{
    // Wait for transfer to start
    while (I2C->I2SR & 0x0080);

    // Wait for transfer to end
    while ((I2C->I2SR & 0x0080) == 0);

    // Set or clear Ack control before last read
    if (cnt > 1)
    { I2C->I2CR &= ~0x0008; }
    else
    { I2C->I2CR |= 0x0008; }

    // Read data
    data[x++] = (unsigned char) I2C->I2DR;
    cnt--;
}

// Wait for transfer to start
while (I2C->I2SR & 0x0080);

// Wait for transfer to end
while ((I2C->I2SR & 0x0080) == 0);

// Signal stop before last read
I2C->I2CR &= ~0x0030;

// Read Read for last data (post stop condition)
data[x++] = (unsigned char) I2C->I2DR;

return x;
}

/*****

I2C_TX()
Transmit byte on bus
ARGS:
    data          : Data to send
RTNS:
    0 = Success
    1 = Failure
*****/

int I2C_TX(unsigned char data)
{
    i2c_map_t* I2C = (i2c_map_t*) I2C_BASE;

    // Send byte
    I2C->I2CR |= 0x0010;          // Tx

    I2C->I2DR = (unsigned short) (data);

    // Wait for transfer to start
    while (I2C->I2SR & 0x0080)
    {
        if (I2C->I2SR & 0x0050)

```

Hardware

```
    { return 1; }
}

// Wait for transfer to end
while ((I2C->I2SR & 0x0080) == 0)
{
    if (I2C->I2SR & 0x0050)
    { return 1; }
}

// Check for Ack
if (I2C->I2SR & 0x0001)
{ return 1; }

return 0;
}

/*****

I2C_WR()
Write a byte to an I2C EEPROM Device. This performs one byte write at a
time to avoid page burst boundary requirements.
ARGS:
    t_addr      : LSB 3-bit address of target device from base address 0xA0.
    b_addr      : Byte address in device
    *data       : Data to write
RTNS:
    0 = Success
    1 = Failure
*****/

int I2C_WR(unsigned char t_addr, unsigned short b_addr, unsigned char *data)
{
    i2c_map_t* I2C = (i2c_map_t*) I2C_BASE;

    // Arbitrate for Bus
    while (I2C->I2SR & 0x0020); // Bus Busy
    I2C->I2CR |= 0x0020; // Master

    // Send device address
    if (I2C_TX(0xA0 | ((t_addr & 7) << 1)))
    { I2C->I2CR &= ~0x0030; return 1; }

    // Send byte address (MSB first)
    if (I2C_TX((unsigned char) (b_addr >> 8)))
    { I2C->I2CR &= ~0x0030; return 1; }
    if (I2C_TX((unsigned char) (b_addr & 0x00ff)))
    { I2C->I2CR &= ~0x0030; return 1; }

    // Send byte data
    if (I2C_TX(*data))
    { I2C->I2CR &= ~0x0030; return 1; }

    // Release Bus
    I2C->I2CR &= ~0x0030; // Slave Rx

    return 0;
}

/*****
I2C_RD()
```

```

Read data from an I2C EEPROM Device
ARGS:
    t_addr      : LSB 3-bit address of target device from base address 0xA0.
    b_addr      : Byte address in device
    *data       : Data to write
    cnt         : number of bytes to read
RTNS:
    Number of bytes read.
*****/

int I2C_RD(unsigned char t_addr, unsigned short b_addr, unsigned char *data,
           int cnt)
{
    i2c_map_t* I2C = (i2c_map_t*) I2C_BASE;
    int x;

    if (cnt < 0)
    { return 0; }

    // Arbitrate for Bus
    while (I2C->I2SR & 0x0020); // Bus Busy
    I2C->I2CR |= 0x0020; // Master

    // Send device address (Keep action a "Write" to set Random Access address)
    if (I2C_TX(0xA0 | ((t_addr & 7) << 1)))
    { I2C->I2CR &= ~0x0030; return 1; }

    // Send byte address (MSB first)
    if (I2C_TX((unsigned char) (b_addr >> 8)))
    { I2C->I2CR &= ~0x0030; return 1; }
    if (I2C_TX((unsigned char) (b_addr & 0x00ff)))
    { I2C->I2CR &= ~0x0030; return 1; }

    I2C->I2CR |= 0x0004; // Restart

    // Send device address (Now send "Read")
    if (I2C_TX(0xA1 | (t_addr << 1)))
    { I2C->I2CR &= ~0x0030; return 1; }

    // Receive a byte data (bus is released by subroutine)
    x = I2C_RX(data, cnt);

    return x;
}

/*****
I2C_EEPROM_INIT()
Write Test Vector Into I2C EEPROM
ARGS:
    (None.)
RTNS:
    0 = Success
    1 = Failure
*****/

int I2C_EEPROM_INIT()
{
    unsigned short x;
    unsigned char y;
    unsigned int retry;

```

Hardware

```
// Init first 1k of EEPROM with sequential numbers (+5, will roll-over)
y = 0;
for (x = 0; x < 1024; x++)
{
    retry = 0;
    while (I2C_WR(0, x, &y))
    {
        retry++;
        if (retry > 150)
        { return 1; }
    }
    y += 5;
}
return 0;
}

/*****

I2C_EEPROM_CHECK()
Check Test Vector In I2C EEPROM
ARGS:
    (None.)
RTNS:
    0 = Success
    1 = Failure
*****/

int I2C_EEPROM_CHECK()
{
    unsigned short x;
    unsigned char y;

    // Read data into buffer
    if (I2C_RD(0, 0, I2C_BUFFER, I2C_BUF_SIZE) != I2C_BUF_SIZE)
    { return 1; }

    // Check first part of EEPROM for sequential numbers (+5, will roll-over)
    y = 0;

    for (x = 0; x < I2C_BUF_SIZE; x++)
    {
        if (I2C_BUFFER[x] != y)
        { return 1; }
        y += 5;
    }
    return 0;
}

/*****

I2C_EEPROM_ERASE()
ERASE I2C EEPROM
ARGS:
    (None.)
RTNS:
    0 = Success
    1 = Failure
*****/

int I2C_EEPROM_ERASE()
{
```

```

unsigned short x;
unsigned char y;
unsigned int retry;

// Init first 1k of EEPROM with 0xFF
y = 0xFF;
for (x = 0; x < 1024; x++)
{
    retry = 0;
    while (I2C_WR(0, x, &y))
    {
        retry++;
        if (retry > 150)
        { return 1; }
    }
}
return 0;
}

```

3.6 Voltage Regulators

Two linear regulator modules on the SPT711xPFCE generate the DDR SDRAM (2.5 VDC) and Ethernet switch core (2.5 V) voltages from the externally supplied 3.3 VDC. A switching regulator generates the MSC711x core (1.2 VDC) voltage from the externally-supplied 5 VDC. **Figure 9** shows how to probe the board voltages.

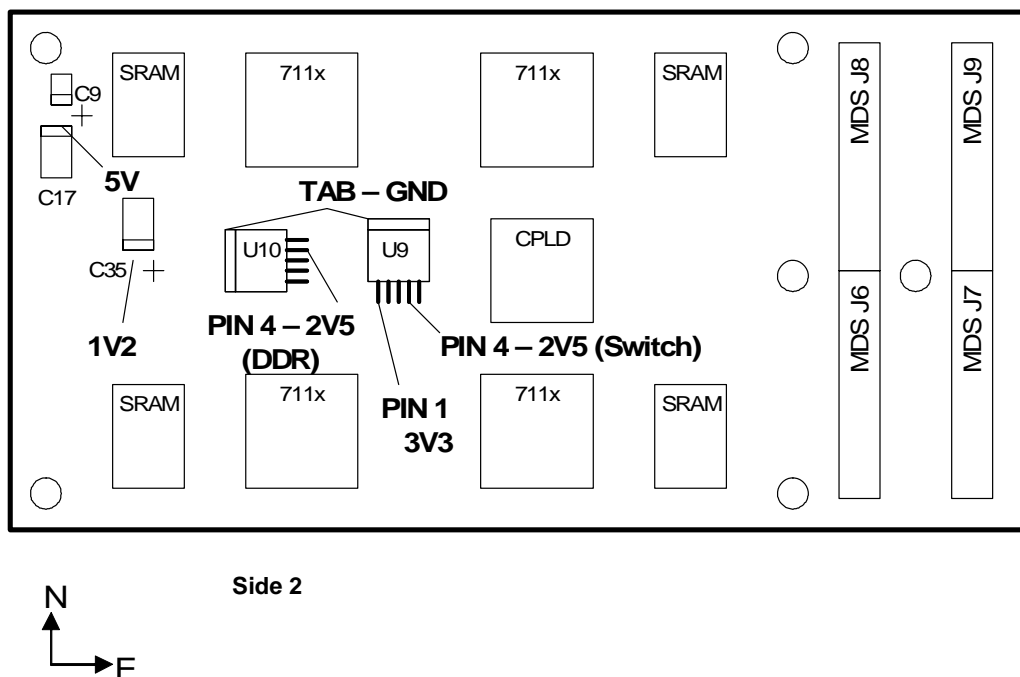


Figure 9. Voltage Probing Points

4 Board Configuration

Some SPT711xPFCE features are not enabled when the board is shipped from the factory. Carefully evaluate the features and their conflicts before enabling them.

4.1 Reset and Boot Mode Selection

The complex programmable logic device (CPLD) controls reset and boot mode selection. It contains the logic necessary to assert $\overline{\text{PORESET}}$ to all four MSC711x devices and individual $\overline{\text{HRESET}}$ to each MSC711x device. The host can also change the boot mode selection signals to all four MSC711x devices. By default, all devices reset to boot mode 0b0000 with SWTE and DBREQ deasserted. For details, see **Section 7, CPLD Registers**, on page 25.

The on-board reset circuitry has been minimized and handles only initial powerup and final powerdown. The circuitry requires a rise/fall time of at least 1 V per 25 ms for both external voltage sources. Also, the external 5 VDC supply must begin rising within 100 ms of the time when the external 3.3 VDC source reaches 2.90 VDC. The reset circuitry issues a $\overline{\text{PORESET}}$ when the external 3.3 VDC source drops below 2.95 VDC or when the 5 VDC source drops below 0.8 VDC. These requirements are reasonable for the board's intended use.

If the external 5 VDC supply is between 0.8 VDC and 3.0 VDC after 200 ms of the external 3.3 VDC reaches 2.95 VDC, the core voltage may “brown out” without triggering a $\overline{\text{PORESET}}$. The host processor must issue a $\overline{\text{PORESET}}$ through the CPLD registers to reset the cores.

4.2 Optional Resistors

Several optional features can be enabled or disabled by installing and/or removing resistors, as detailed in **Table 5**.

Table 5. Optional Resistors

Resistor	Option
R181 (R179)	JTAG Chain Bypass CPLD
R2 (R1)	JTAG Chain Bypass SL0
R8 (R5)	JTAG Chain Bypass SL1
R285 (R54)	JTAG Chain Bypass SL2
R40 (R41)	JTAG Chain Bypass SL3
R121 (R78)	TPSEL = 0 SL0
R124 (R15)	TPSEL = 0 SL1
R56 (R55)	TPSEL = 0 SL2
R51 (R52)	TPSEL = 0 SL3
U6 (R148, R135)	SPI EEPROM SL0
U3 (R150, R97)	SPI EEPROM SL1
U14 (R221, R244)	SPI EEPROM SL2

Table 5. Optional Resistors (continued)

Resistor	Option
U18 (R301, R295)	SPI EEPROM SL3
R161, R26, R233, R236	Via Switch Boot Mode
Note: Components in () should be removed when the others are installed, and <i>vice versa</i> . For details, see the schematics.	

5 Board Specifications

Figure 10 shows a detailed mechanical drawing of the SPT711xPFCE. These dimensions conform to the CMC standard length and width dimensions. Board height varies according to the components on the board and choice of CMC connector height. Estimated board height is 13.5 mm unless both sets of CMC connectors are populated. If CMC connectors are populated on both sides of the board, the estimated board height is 24 mm.

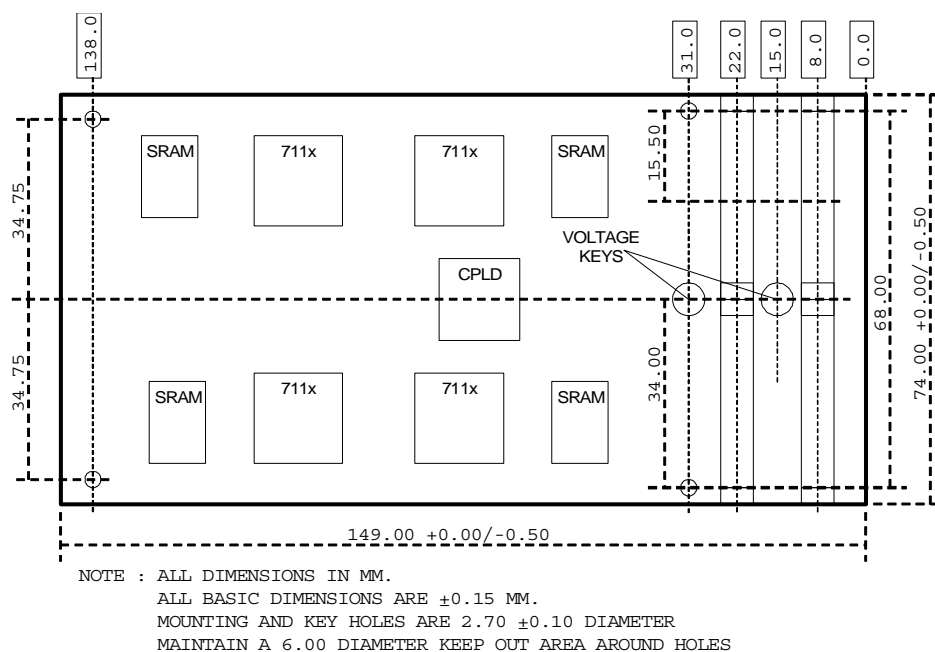


Figure 10. SPT711xPFCE Board Mechanical Dimensions

Table 6 shows the results of SPT711xPFCE power measurements.

Table 6. Power Consumption

Description	3.3 VDC	5.0 VDC	Units
Idle:			
Approximate current	0.56	0.23	Amps
Approximate power	1.8	1.1	Watts
Total approximate power	3.0		Watts

Table 6. Power Consumption (continued)

Description	3.3 VDC	5.0 VDC	Units
One core DMA:			
Approximate current	0.58	0.26	Amps
Approximate power	1.9	1.3	Watts
Total approximate power	3.2		Watts
One core flood ping:			
Approximate current	0.78	0.23	Amps
Approximate power	2.5	1.1	Watts
Total approximate power	3.7		Watts
All cores DMA and ping:			
Approximate current	1.0	0.39	Amps
Approximate power	3.4	1.9	Watts
Total approximate power	5.3		Watts
<p>Note: Power measurements were taken on a PDK base board using external power supplies. The test environment was room temperature (approximately 25°C). The values provided include a 10 percent guard band above the test results. The DMA test runs at approximately 80 Mbps (read and write transfers together) and includes a 1 Kbyte block 32-bit checksum calculation and check. The flood ping test is performed by rapidly sending ICMP echo requests from a host processor to each DSP core. The cores respond with ICMP echo replies.</p>			

6 CPLD Memory Map

The system memory map is determined by the CPLD on the SPT711xPFCE, as shown in **Table 7**.

Table 7. SPT711xPFCE System Memory Map

Register	Offset	Description
DSP1		First digital signal processor
ICR	0x00000	HDI16 interface control register
CVR	0x00002	HDI16 command vector register
ISR	0x00004	HDI16 interface status register
Tx/Rx[0–3]	0x02000	HDI16 transmit/receive data registers
DSP2		Second digital signal processor
ICR	0x08000	HDI16 interface control register
CVR	0x08002	HDI16 command vector register
ISR	0x08004	HDI16 interface status register
Tx/Rx[0–3]	0x0A000	HDI16 transmit/receive data registers
DSP3		Third digital signal processor
ICR	0x10000	HDI16 interface control register
CVR	0x10002	HDI16 command vector register
ISR	0x10004	HDI16 interface status register
Tx/Rx[0–3]	0x12000	HDI16 transmit/receive data registers
DSP4		Fourth digital signal processor
ICR	0x18000	HDI16 interface control register
CVR	0x18002	HDI16 command vector register

Table 7. SPT711xPFCE System Memory Map (continued)

Register	Offset	Description
ISR	0x18004	HDI16 interface status register
Tx/Rx[0–3]	0x1A000	HDI16 transmit/receive data registers
DSP broadcast		All four digital signal processors
ICR	0x20000	HDI16 interface control register
CVR	0x20002	HDI16 command vector register
ISR	0x20004	HDI16 interface status register
Tx/Rx[0–3]	0x22000	HDI16 transmit/receive data registers
Ethernet switch		Ethernet switch control registers
PMDATA	0x28000	16-bit packet or memory data
RDATA	0x28002	8-bit register data
ADDRL	0x28004	Low byte of 16-bit address
ADDRH	0x28006	High byte of 16-bit address
CPLD Registers		Internal 8-bit CPLD control registers
RCSR	0x38000	Reset control/status register
BMCR	0x38002	Boot mode control register
HSR	0x38004	HREQ status register
HER	0x38006	HREQ enable register
ISR	0x3A000	IRQ from DSP status register
IER	0x3A002	IRQ from DSP enable register
—	0x3A004	Reserved
FVR	0x3A006	Firmware version register

7 CPLD Registers

The CPLD registers are implemented inside the CPLD firmware and control many functions of the board, including DSP reset and interrupt generation. The registers discussed in this section are as follows:

- Reset control and status register (RCSR), page 26
- Boot mode control register (BMCR), page 26
- HREQ status register (HSR), page 27
- HREQ enable register (HER), page 27
- Interrupt from DSP status register (ISR), page 28
- Interrupt from DSP enable register (IER), page 28
- Firmware version register (FVR), page 28

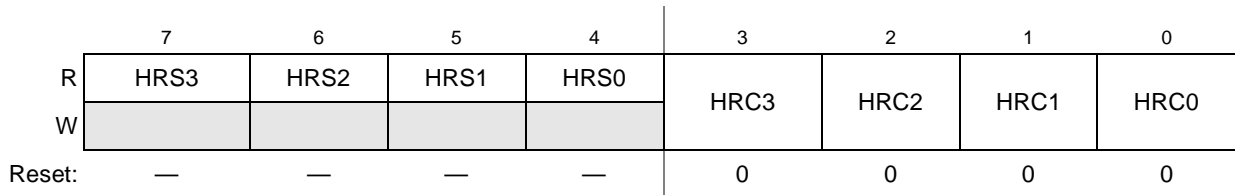


Figure 7-11. Reset Control and Status Register (RCSR)

Table 7-8. RCSR Bit Descriptions

Bits	Name	Description	Settings
7–4	HRS[3–0]	$\overline{\text{HRESET}}$ status from DSP[3–0]. Indicates the state of the $\overline{\text{HRESET}}$ signal from each of the MSC711x devices.	0 $\overline{\text{HRESET}}$ is asserted. 1 $\overline{\text{HRESET}}$ is deasserted.
3–0	HRC[3–0]	$\overline{\text{HRESET}}$ command to DSP[3–0]. Controls the value driven by the CPLD onto each $\overline{\text{HRESET}}$ signal to each MSC711x device.	0 CPLD does not drive signal. 1 CPLD asserts signal.

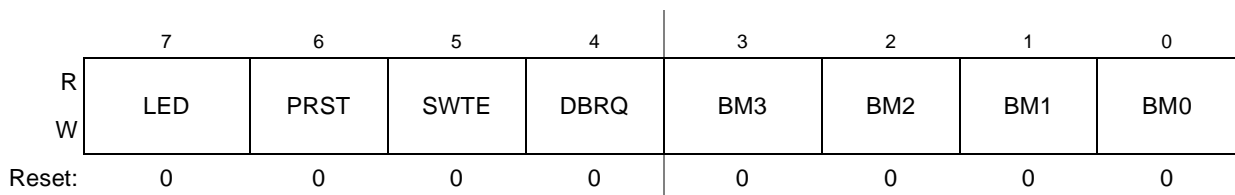


Figure 7-12. Boot Mode Control Register (BMCR)

Table 7-9. BMCR Bit Descriptions

Bits	Name	Description	Settings
7	LED	LED on. Illuminates the LED on the SPT711xPFCE connected to the CPLD.	0 CPLD LED is not on. 1 CPLD LED is on.
6	PRST	Power reset control and status. When read, this bit indicates the state of the $\overline{\text{PORESET}}$ signal to all four MSC711x devices. When written, this bit controls the value driven by the CPLD onto the $\overline{\text{PORESET}}$ signal.	Read: 0 $\overline{\text{PORESET}}$ is deasserted. 1 $\overline{\text{PORESET}}$ is asserted. Write: 0 CPLD does not drive signal. 1 CPLD asserts signal.
5	SWTE	SWTE control. Controls the value driven by the CPLD onto the SWTE signal to the MSC711x devices when $\overline{\text{PORESET}}$ is asserted.	0 SWTE is logic low. 1 SWTE is logic high.
4	DBRQ	DBREQ control. Controls the value driven by the CPLD onto the DBREQ signal to the MSC711x devices when $\overline{\text{PORESET}}$ is asserted.	0 DBREQ is logic low. 1 DBREQ is logic high.
3–0	BM[3–0]	BM[3–0] control. Controls the value driven by the CPLD onto the BM[3–0] signals to the MSC711x devices when $\overline{\text{PORESET}}$ is asserted.	



Figure 7-13. HREQ Status Register (HSR)

Table 7-10. HSR Bit Descriptions

Bits	Name	Description	Settings
7–4	HRRQ[3–0]	HRRQ status from DSP[3–0]. Indicates the state of the HRRQ signal from each of the MSC711x devices.	0 HRRQ is logic low. 1 HRRQ is logic high.
3–0	HTRQ[3–0]	HTRQ status from DSP[3–0]. Indicates the state of the HTRQ signal from each of the MSC711x devices.	0 HTRQ is logic low. 1 HTRQ is logic high.

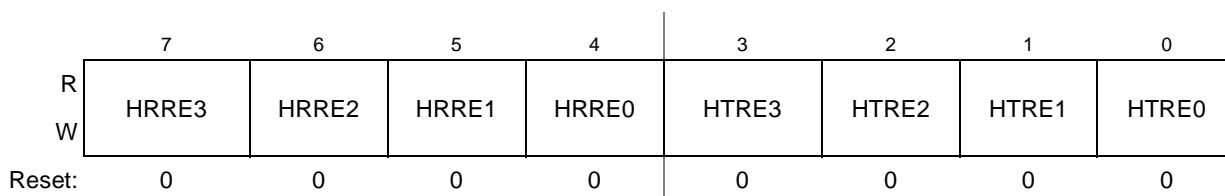


Figure 7-14. HREQ Enable Register (HER)

Table 7-11. HER Bit Descriptions

Bits	Name	Description	Settings
7–4	HRRE[3–0]	DSP[3–0] HRRQ enable. Determines whether an HRRQ signal from an MSC711x device is used to signal the global active low HRRQ signal to the host.	0 HRRQ is not enabled. 1 HRRQ is enabled.
3–0	HTRE[3–0]	DSP[3–0] HTRQ enable. Determines whether an HTRQ signal from an MSC711x device is used to signal the global active low HTRQ signal to the host.	0 HTRQ is not enabled. 1 HTRQ is enabled.

Note: The CPLD firmware is written to enable/disable the HRRQ and HTRQ signals properly when they are configured as active low out of the MSC711x devices. If only one device is enabled at a time, the signal polarity does not matter.

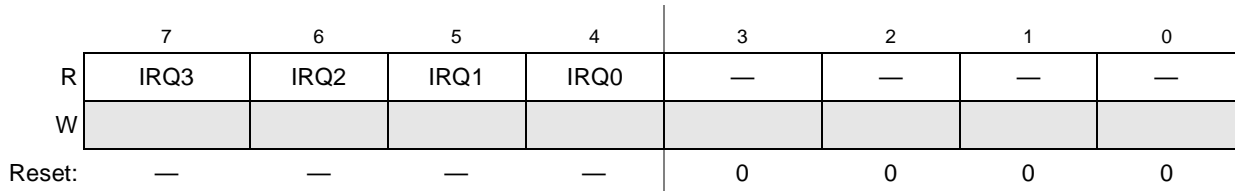


Figure 7-15. Interrupt from DSP Status Register (ISR)

Table 7-12. ISR Bit Descriptions

Bits	Name	Description	Settings
7–4	IRQ[3–0]	Interrupt request from DSP[3–0]. Shows the interrupt status from each MSC711x device. The Event2 pin from each MSC711x device signals interrupts to the host.	0 Requesting interrupt. 1 Not requesting interrupt.
3–0	—	Reserved. Cleared to zero for future compatibility.	

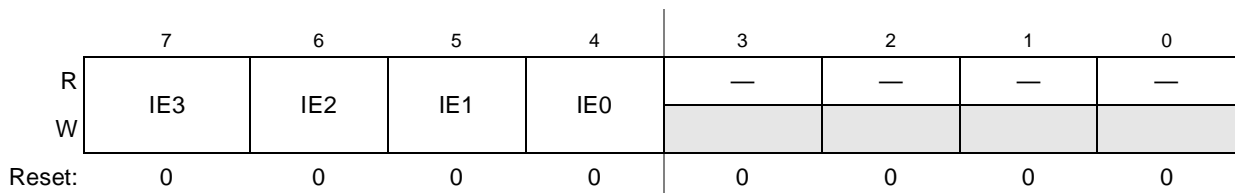


Figure 7-16. Interrupt from DSP Enable Register (IER)

Table 7-13. IER Bit Descriptions

Bits	Name	Description	Settings
7–4	IE[3–0]	Interrupt request from DSP[3–0] enable. Determines whether an IRQ signal from an MSC711x device is used to signal the global active low IRQ signal to the host.	0 Request is disabled. 1 Request is enabled.
3–0	—	Reserved. Cleared to zero for future compatibility.	

Note: The CPLD firmware is written to enable/disable the IRQ signals properly when they are configured as active low out of the MSC711x devices. If only one device is enabled at a time, the signal polarity does not matter.

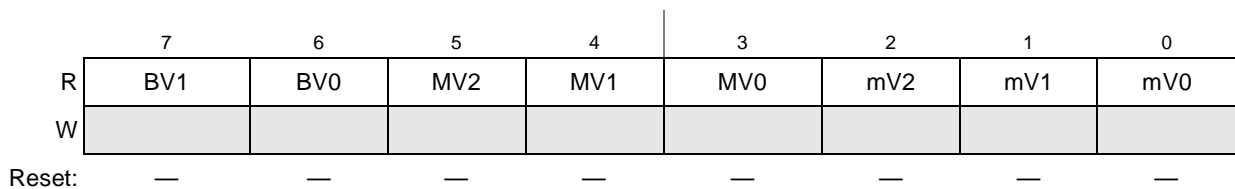


Figure 7-17. Firmware Version Register (FVR)

Table 7-14. FVR Bit Descriptions

Bits	Name	Description	Settings
7–6	BV[1–0]	Board version. Indicates the board revision level as programmed into the CPLD firmware.	
5–3	MV[2–0]	Major version. Indicates the firmware major revision level.	
2–0	mV[2–0]	Minor version. Indicates the firmware minor revision level.	

Appendix A CPLD Firmware

```

/* Copyright 2005, All Rights Reserved, Freescale Semiconductor, Inc. */
/*****
PROJECT   : MSC711xPFC Revision 2 CPLD (Xilinx XC9572XL-10TQG100C)
MODULE    : TOPLEVEL

NOTES     : All bus control signals are active-low (CS, DS, RW, etc.).

AUTHOR    : David M. Koltak 10/17/2005

```

VER	DATE	AUTHOR	-DESCRIPTION
0.1	10/17/2005	David M. Koltak	-Initial Design
1.0	10/18/2005	David M. Koltak	-Compiles without warnings or errors
1.1	10/19/2005	David M. Koltak	-IDMA Mode, BM Reset I2C, Clock Loop
1.2	10/19/2005	David M. Koltak	-Changed BM0 so default=0, output=1
1.3	11/07/2005	David M. Koltak	-Changed default BM back to 0x0 -Changed clock assignments
2.0	01/30/2006	David M. Koltak	-Changed HDREQ equations -Added Firmware Version Register -Removed IDMA Mode
3.0	04/19/2006	David M. Koltak	-Updated for production boards (V2.7)

```

*****/
#define BOARD_VERSION 2'd1
#define MAJOR_VERSION 3'd3
#define MINOR_VERSION 3'd0

```

```

module TOPLEVEL
(
    CLKIN,
    DSP_CLKIN,
    PORESET,

    GOOD_3V3,
    GOOD_5V,
    LED,

    EONCE_HRESET,
    DSP_HRESET,
    DSP_BM0,
    DSP_BM,
    DSP_SWTE,
    DSP_DBREQ,

    DSP_HTRQ,
    DSP_HRRQ,
    HDREQ,

    DSP_HA,
    HA_DSP,

```

```

DSP_HD,
HCS,
HRW,
HDS,

DSP_HDS,
DSP_HRW,
DSP_BHCS,
DSP_HCS,
SWCH_HCS,

MDS_IRQ_OUT,
PDK_IRQ_OUT,
SWCH_IRQ,
TP
);

// External Pin Definitions
input          CLKIN;
output [3:0]   DSP_CLKIN;
output        PORESET;
input        GOOD_3V3;
input        GOOD_5V;
output        LED;

input          EONCE_HRESET;
input [3:0]    DSP_HRESET;
output [3:0]   DSP_BM0;
output [3:1]   DSP_BM;
output        DSP_SWTE;
output        DSP_DBREQ;

input [3:0]    DSP_HTRQ;
input [3:0]    DSP_HRRQ;
output [2:1]   HDREQ;

input [2:0]    DSP_HA;
input [0:2]    HA_DSP;
input [7:0]    DSP_HD;
input        HCS;
input        HRW;
input        HDS;
output       DSP_HDS;
output       DSP_HRW;
output       DSP_BHCS;
output [3:0]   DSP_HCS;
output       SWCH_HCS;

output        MDS_IRQ_OUT;
output        PDK_IRQ_OUT;
output        SWCH_IRQ;
output [1:0]   TP;

```

```

// Internal Module Signals/Registers
reg          m_int_cs;
reg          m_swch_hcs;
reg          m_dsp_bhcs;
reg [3:0]    m_dsp_hcs;
wire         m_int_we;
wire         m_int_oe;
reg          m_dsp_hds;
reg          m_dsp_hrw;

reg          m_led_out;
reg          m_poreset_out;
wire         m_poreset;
reg [3:0]    m_hreset_out;
wire [3:0]   m_hreset;
reg          m_swte_out;
reg          m_dbreq_out;
reg [3:0]    m_bm_out;
wire [3:0]   m_bm0;
reg [7:0]    m_hreq_en;
reg [3:0]    m_dsp_irq_en;
wire         m_dsp_irq;
wire [3:0]   m_dsp_irq_in;
reg [7:0]    m_data_out;

// Assign Internal to/from External Signals
assign DSP_CLKIN[0] = CLKIN;
assign DSP_CLKIN[1] = !CLKIN;
assign DSP_CLKIN[2] = CLKIN;
assign DSP_CLKIN[3] = !CLKIN;

assign TP[1:0] = 2'b00;

assign LED = m_led_out;

assign m_poreset = (GOOD_3V3 | (!GOOD_5V) | m_poreset_out) ? 1'b0 : 1'b1;
assign PORESET = m_poreset;
assign m_bm0[0] = (m_poreset) ? 1'bz : m_bm_out[0];
assign m_bm0[1] = (m_poreset) ? 1'bz : m_bm_out[0];
assign m_bm0[2] = (m_poreset) ? 1'bz : m_bm_out[0];
assign m_bm0[3] = (m_poreset) ? 1'bz : m_bm_out[0];
assign DSP_BM0[0] = m_bm0[0];
assign DSP_BM0[1] = m_bm0[1];
assign DSP_BM0[2] = m_bm0[2];
assign DSP_BM0[3] = m_bm0[3];
assign DSP_BM[1] = m_bm_out[1];
assign DSP_BM[2] = m_bm_out[2];
assign DSP_BM[3] = m_bm_out[3];
assign DSP_SWTE = m_swte_out;
assign DSP_DBREQ = m_dbreq_out;

assign m_hreset[0] = (m_hreset_out[0] | (!EONCE_HRESET)) ? 1'b0 : 1'bz;
assign m_hreset[1] = (m_hreset_out[1] | (!EONCE_HRESET)) ? 1'b0 : 1'bz;

```



```

assign m_hreset[2] = (m_hreset_out[2] | (!EONCE_HRESET)) ? 1'b0 : 1'bz;
assign m_hreset[3] = (m_hreset_out[3] | (!EONCE_HRESET)) ? 1'b0 : 1'bz;
assign DSP_HRESET = m_hreset;

assign HDREQ[2] = (DSP_HRRQ[3] | (!m_hreq_en[7])) &
                 (DSP_HRRQ[2] | (!m_hreq_en[6])) &
                 (DSP_HRRQ[1] | (!m_hreq_en[5])) &
                 (DSP_HRRQ[0] | (!m_hreq_en[4]));

assign HDREQ[1] = (DSP_HTRQ[3] | (!m_hreq_en[3])) &
                 (DSP_HTRQ[2] | (!m_hreq_en[2])) &
                 (DSP_HTRQ[1] | (!m_hreq_en[1])) &
                 (DSP_HTRQ[0] | (!m_hreq_en[0]));

assign m_dsp_irq_in[3:0] = ~(DSP_BM0[3:0]); // Bitwise Not
assign m_dsp_irq = (m_dsp_irq_in[3] | (!m_dsp_irq_en[3])) &
                  (m_dsp_irq_in[2] | (!m_dsp_irq_en[2])) &
                  (m_dsp_irq_in[1] | (!m_dsp_irq_en[1])) &
                  (m_dsp_irq_in[0] | (!m_dsp_irq_en[0]));

assign MDS_IRQ_OUT = (m_dsp_irq) ? 1'b0 : 1'bz;
assign PDK_IRQ_OUT = (m_dsp_irq) ? 1'b0 : 1'bz;
assign SWCH_IRQ = 1'b1;

// DSP/Switch Bus Control (Single or Dual Strobe)
assign DSP_HDS = m_dsp_hds;
assign DSP_HRW = m_dsp_hrw;
always @ *
begin
    if (!m_swch_hcs) // Dual Strobe for Switch
        begin
            m_dsp_hds = HDS | HRW; // #IOW
            m_dsp_hrw = HDS | (!HRW); // #IOR
        end
    else // Single Strobe for DSPs
        begin
            m_dsp_hds = HDS;
            m_dsp_hrw = HRW;
        end
end

// Chip Select Logic
// 0-3 : DSP 0-3
// 4 : DSP Broadcast
// 5 : Ethernet Switch
// 7 : CPLD Registers
assign SWCH_HCS = m_swch_hcs;
assign DSP_BHCS = m_dsp_bhcs;
assign DSP_HCS = m_dsp_hcs;
always @ *
begin
    case (HA_DSP)
        3'd0: {m_int_cs, m_swch_hcs, m_dsp_bhcs, m_dsp_hcs} <= {6'b111111, HCS};
    endcase
end

```

```

3'd1: {m_int_cs, m_swch_hcs, m_dsp_bhcs, m_dsp_hcs} <= {5'b11111, HCS, 1'b1};
3'd2: {m_int_cs, m_swch_hcs, m_dsp_bhcs, m_dsp_hcs} <= {4'b1111, HCS, 2'b11};
3'd3: {m_int_cs, m_swch_hcs, m_dsp_bhcs, m_dsp_hcs} <= {3'b111, HCS, 3'b111};
3'd4: {m_int_cs, m_swch_hcs, m_dsp_bhcs, m_dsp_hcs} <= {2'b11, HCS, 4'b1111};
3'd5: {m_int_cs, m_swch_hcs, m_dsp_bhcs, m_dsp_hcs} <= {1'b1, HCS, 5'b11111};
// No 6, default.
3'd7: {m_int_cs, m_swch_hcs, m_dsp_bhcs, m_dsp_hcs} <= {HCS, 6'b111111};
default: {m_int_cs, m_swch_hcs, m_dsp_bhcs, m_dsp_hcs} <= 7'b1111111;
endcase
end

// Internal Registers (Write Logic)
assign m_int_we = (m_int_cs | HDS | HRW);
always @ (negedge m_int_we or negedge GOOD_3V3)
begin
    if (!GOOD_3V3)
    begin
        m_led_out <= 1'b0;
        m_poreset_out <= 1'd0;
        m_hreset_out <= 4'd0;
        m_swte_out <= 1'd0;
        m_dbreq_out <= 1'd0;
        m_bm_out <= 4'd0;
        m_hreq_en <= 8'd0;
        m_dsp_irq_en <= 4'd0;
    end
    else
    begin
        case (DSP_HA)
        // RESET CONTROL/STATUS REGISTER
        3'd0: {m_hreset_out} <= DSP_HD[3:0];
        // BOOT MODE CONTROL REGISTER
        3'd1: {m_led_out, m_poreset_out, m_swte_out,
            m_dbreq_out, m_bm_out} <=
{DSP_HD[7:0]};
        // HREQ ENABLE REGISTER
        3'd3: m_hreq_en <= DSP_HD[7:0];
        // IRQ FROM DSP ENABLE REGISTER
        3'd5: m_dsp_irq_en <= DSP_HD[7:4];
        default: ;
        endcase
    end
end

// Internal Registers and Status (Read Logic)
assign DSP_HD = m_data_out;
assign m_int_oe = (m_int_cs | HDS | (!HRW));
always @ *
begin
    if (m_int_oe)
    begin
        m_data_out <= 8'hzz;
    end
end

```

```
else
begin
  case (DSP_HA)
  // RESET CONTROL/STATUS REGISTER
  3'd0: m_data_out <= {DSP_HRESET, m_hreset_out};
  // BOOT MODE CONTROL REGISTER
  3'd1: m_data_out <= {m_led_out, (!PORESET), m_swte_out,
                      m_dbreq_out, m_bm_out[3:0]};

  // HREQ STATUS REGISTER
  3'd2: m_data_out <= {DSP_HRRQ, DSP_HTRQ};
  // HREQ ENABLE REGISTER
  3'd3: m_data_out <= m_hreq_en;
  // IRQ FROM DSP STATUS REGISTER
  3'd4: m_data_out <= {m_dsp_irq_in, 4'd0};
  // IRQ FROM DSP ENABLE REGISTER
  3'd5: m_data_out <= {m_dsp_irq_en, 4'd0};
  // FIRMWARE VERSION REGISTER
  3'd7: m_data_out <= {'BOARD_VERSION, 'MAJOR_VERSION, 'MINOR_VERSION};
  default: m_data_out <= 8'd0;
  endcase
end
end

endmodule
```

Appendix B SPT711xPFCE Schematics



**MSC711xPFC
Revision 2.x**

The MSC711xPFC is a Packet-Telephony Farm card based on the MSC711x family of devices from Freescale Semiconductor. It combines four MSC7116 devices sharing an HDI16 bus and aggregated with an on board Ethernet switch.

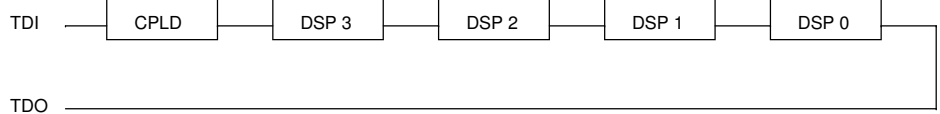
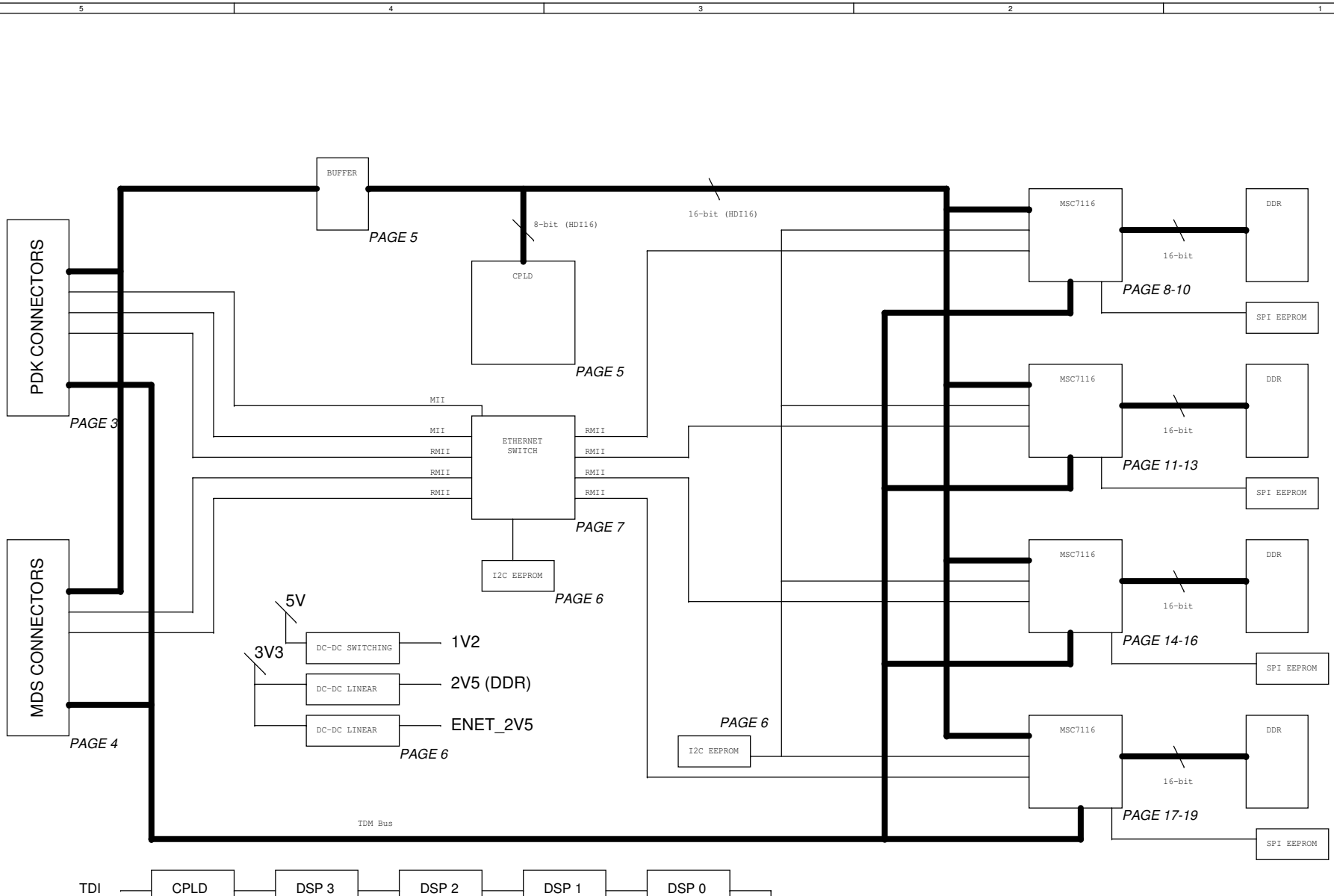
PAGES

- 1.) TITLE
- 2.) BLOCK DIAGRAM
- 3.) PDK CONNECTORS
- 4.) MDS CONNECTORS
- 5.) HDI16 / BUFFERS
- 6.) POWER / RESET
- 7.) ENET SWITCH
- 8.) DSP0 SYS
- 9.) DSP0 DDR
- 10.) DSP0 PWR
- 11.) DSP1 SYS
- 12.) DSP1 DDR
- 13.) DSP1 PWR
- 14.) DSP2 SYS
- 15.) DSP2 DDR
- 16.) DSP2 PWR
- 17.) DSP3 SYS
- 18.) DSP3 DDR
- 19.) DSP3 PWR

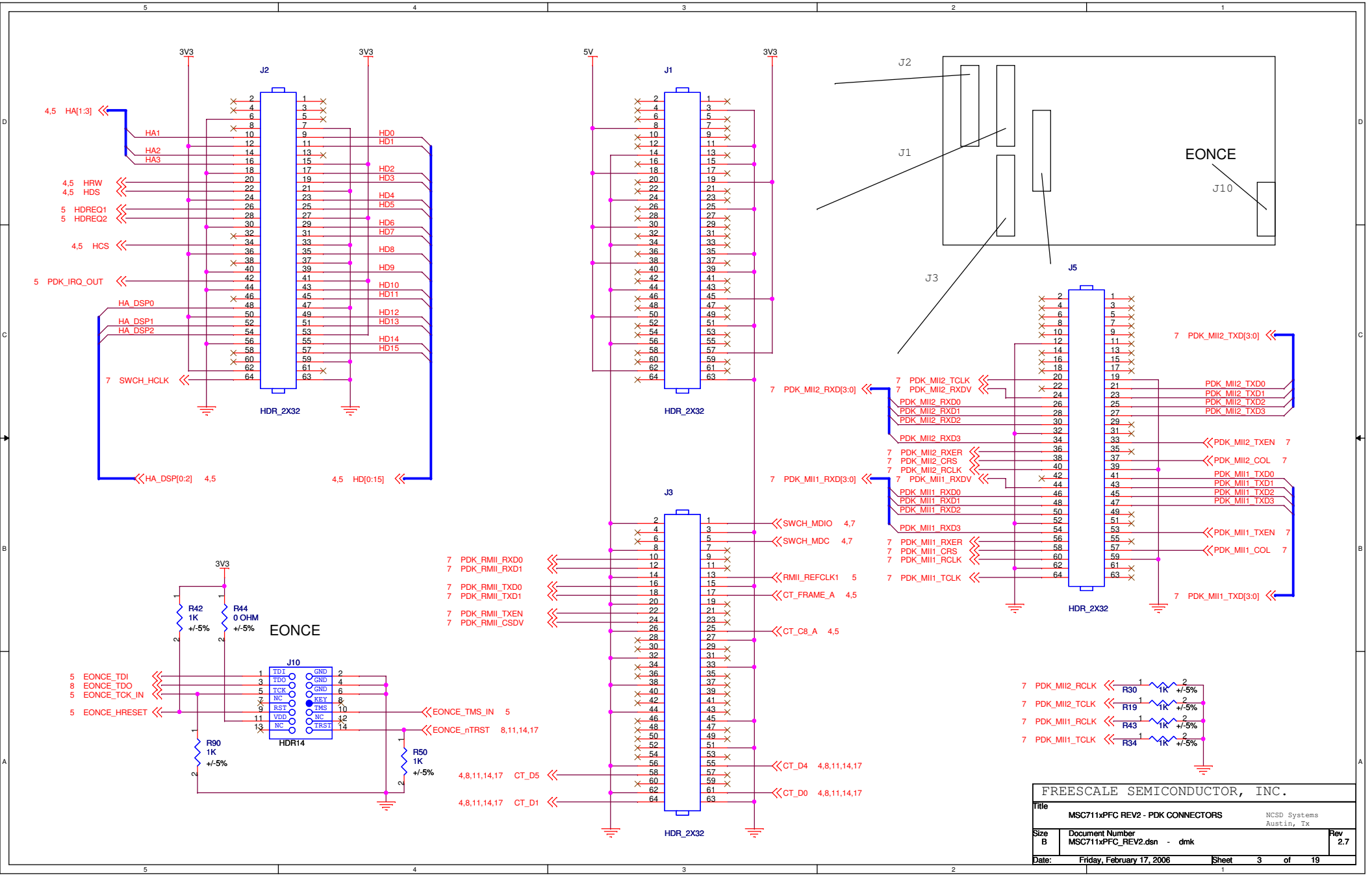
VERSION HISTORY

VER	DATE	AUTHOR	-COMMENTS
2.0	07/25/2005	David M. Koltak	-Initial Design
2.1	08/05/2005	David M. Koltak	-Zero-Delay Buffer
2.2	08/12/2005	David M. Koltak	-Enet2V5
2.3	08/18/2005	David M. Koltak	-J10 Part Changed & DNPs
2.4	09/13/2005	David M. Koltak	-Enet Boot Strap, TPs, nTRST P/D, PMC Molex
2.5	09/19/2005	David M, Koltak	-Agile 0.1uF Caps, Ref's
----- PROTOTYPES -----			
2.6	11/14/2005	David M. Koltak	-Reset, MII, LED, J10
2.7	01/27/2006	David M. Koltak	-I2C Pull Ups

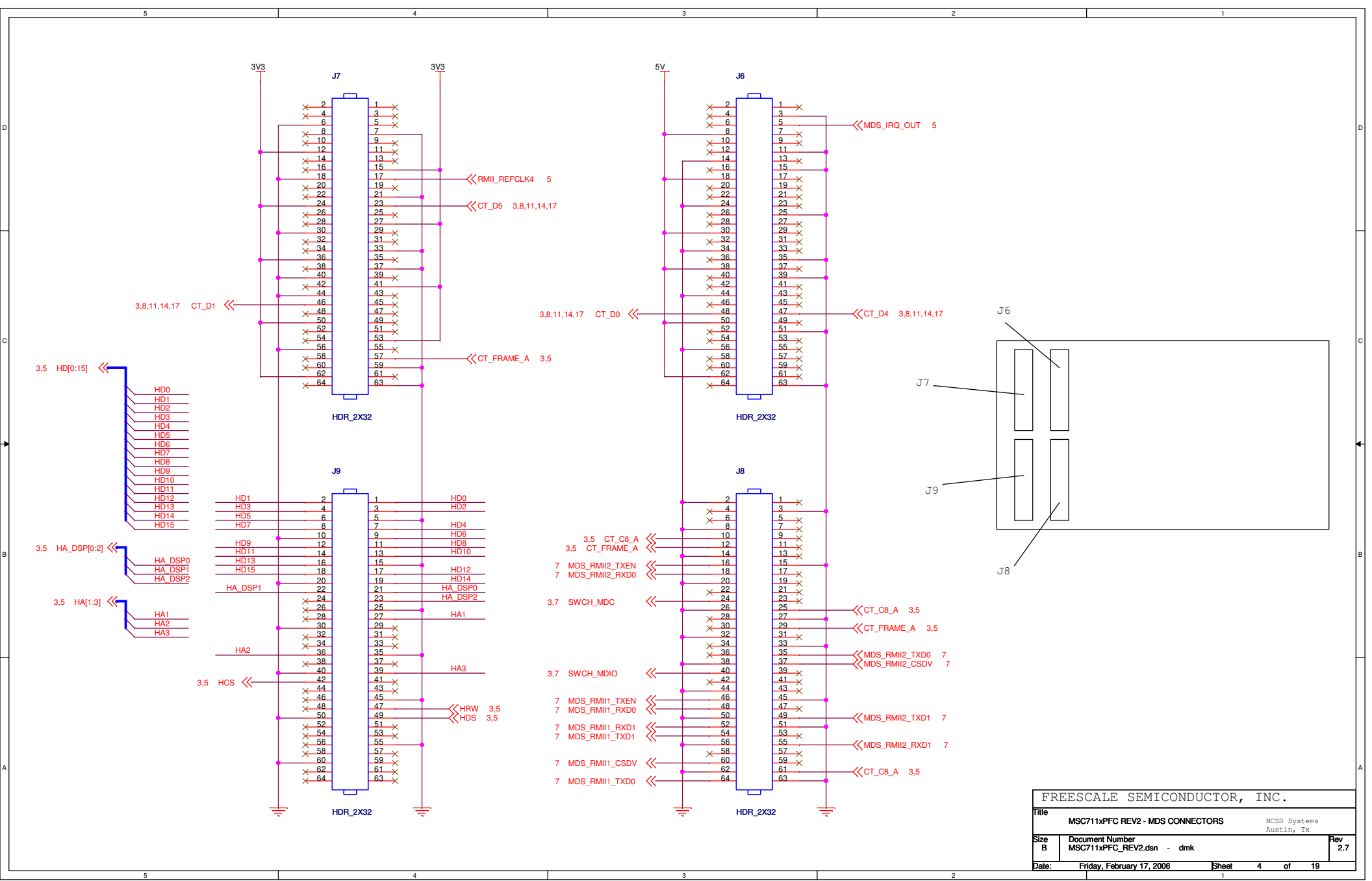
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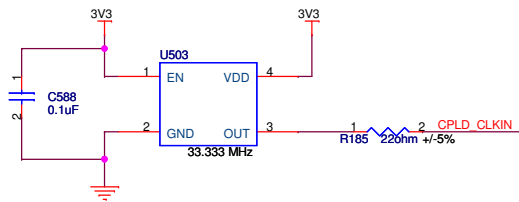


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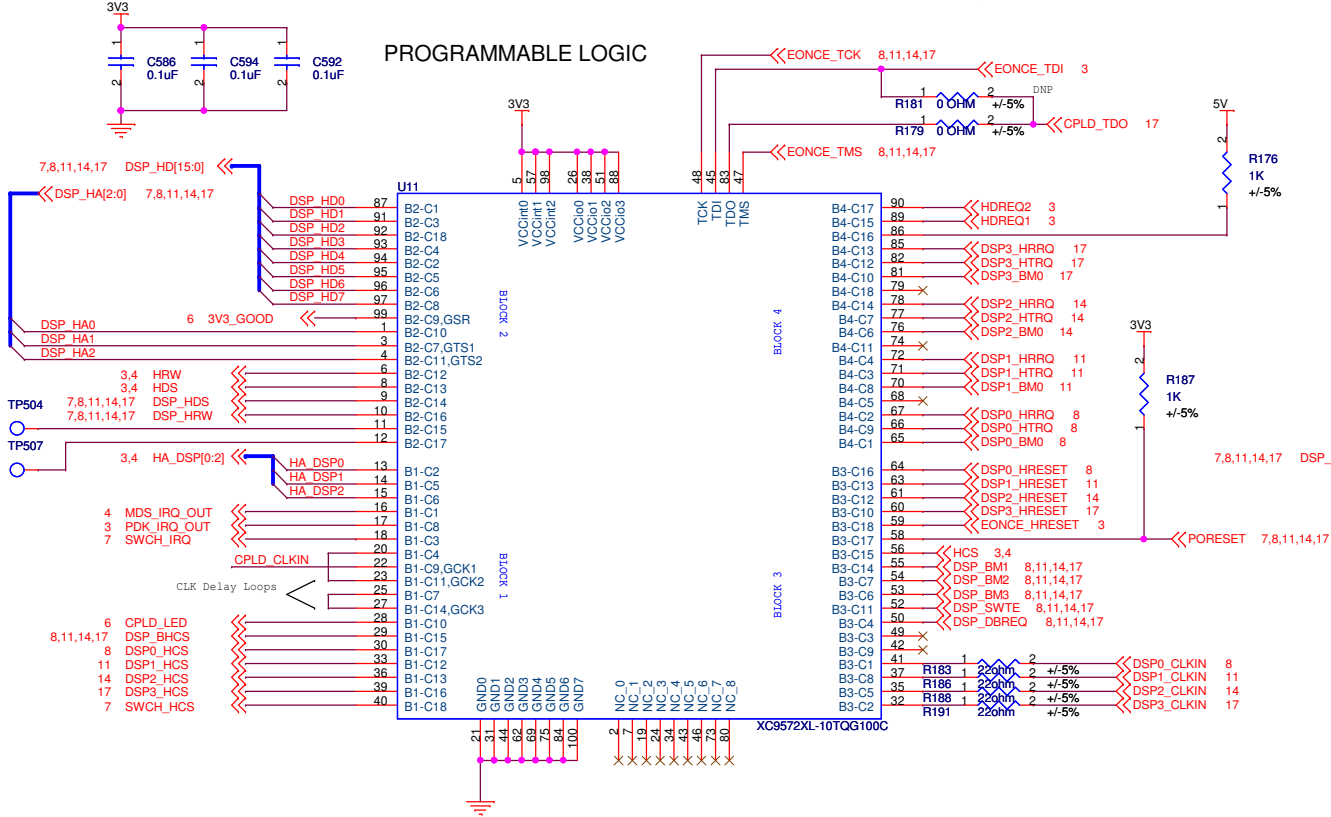


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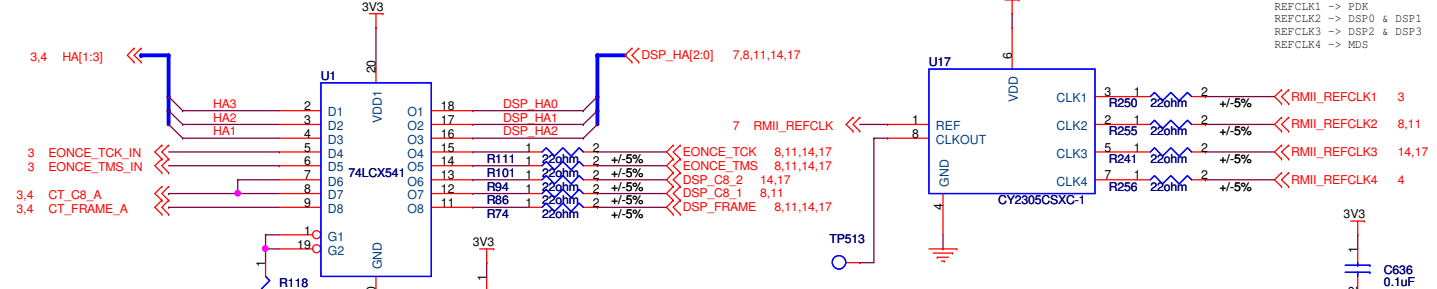
OSCILLATOR



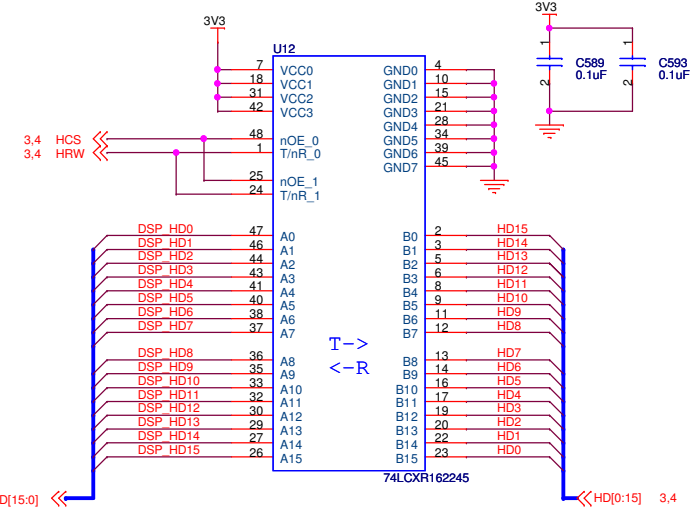
PROGRAMMABLE LOGIC



SIGNAL BUFFERS

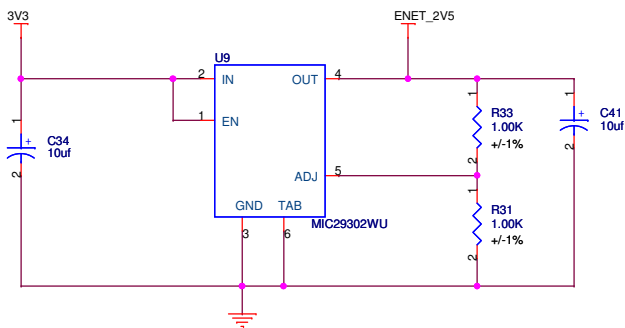


HDI16 BUS BUFFER

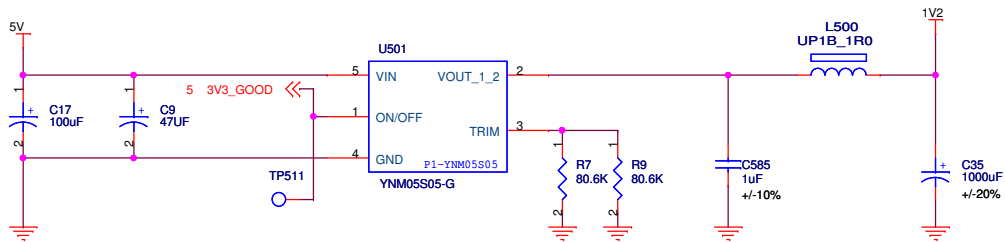


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ENET SWITCH 2.5 V POWER (3A)

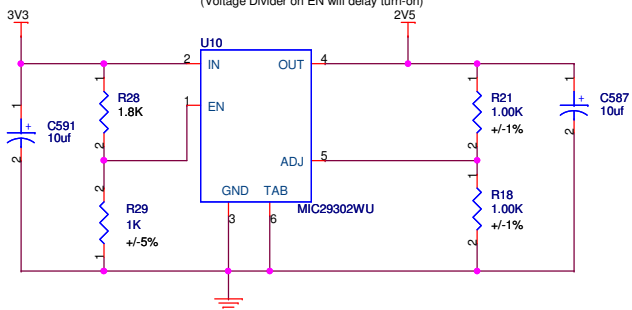


MSC711x 1.2V CORE POWER (5A)



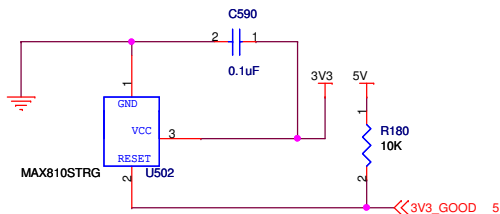
DDR 2.5 V POWER (3A)

(Voltage Divider on EN will delay turn-on)

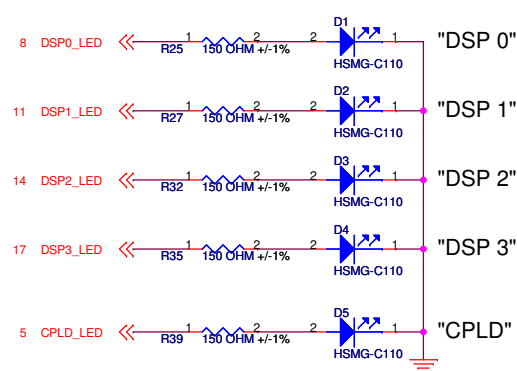


3V3 VOLTAGE DETECTOR

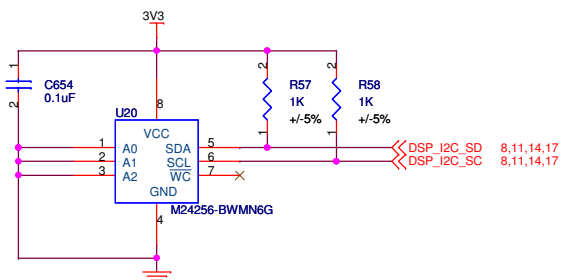
(Turn on 1V2 240ms after 3V3 reaches 2.93V)



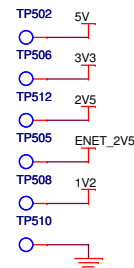
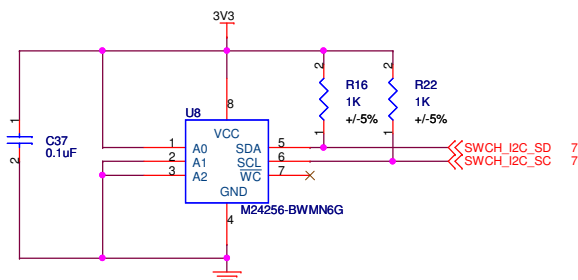
INDICATORS



DSP I2C BOOT EEPROM

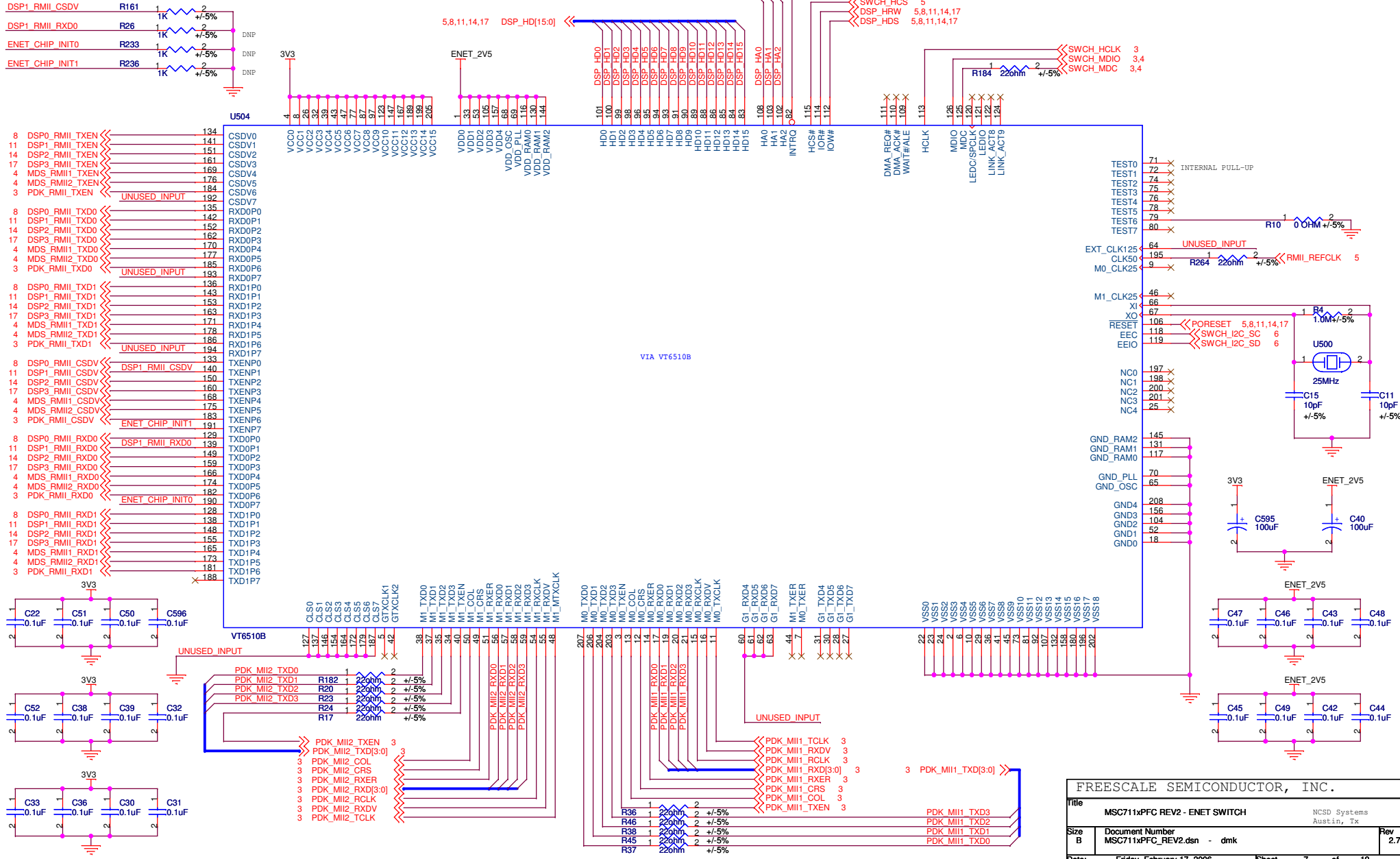


ENET SWITCH BOOT EEPROM

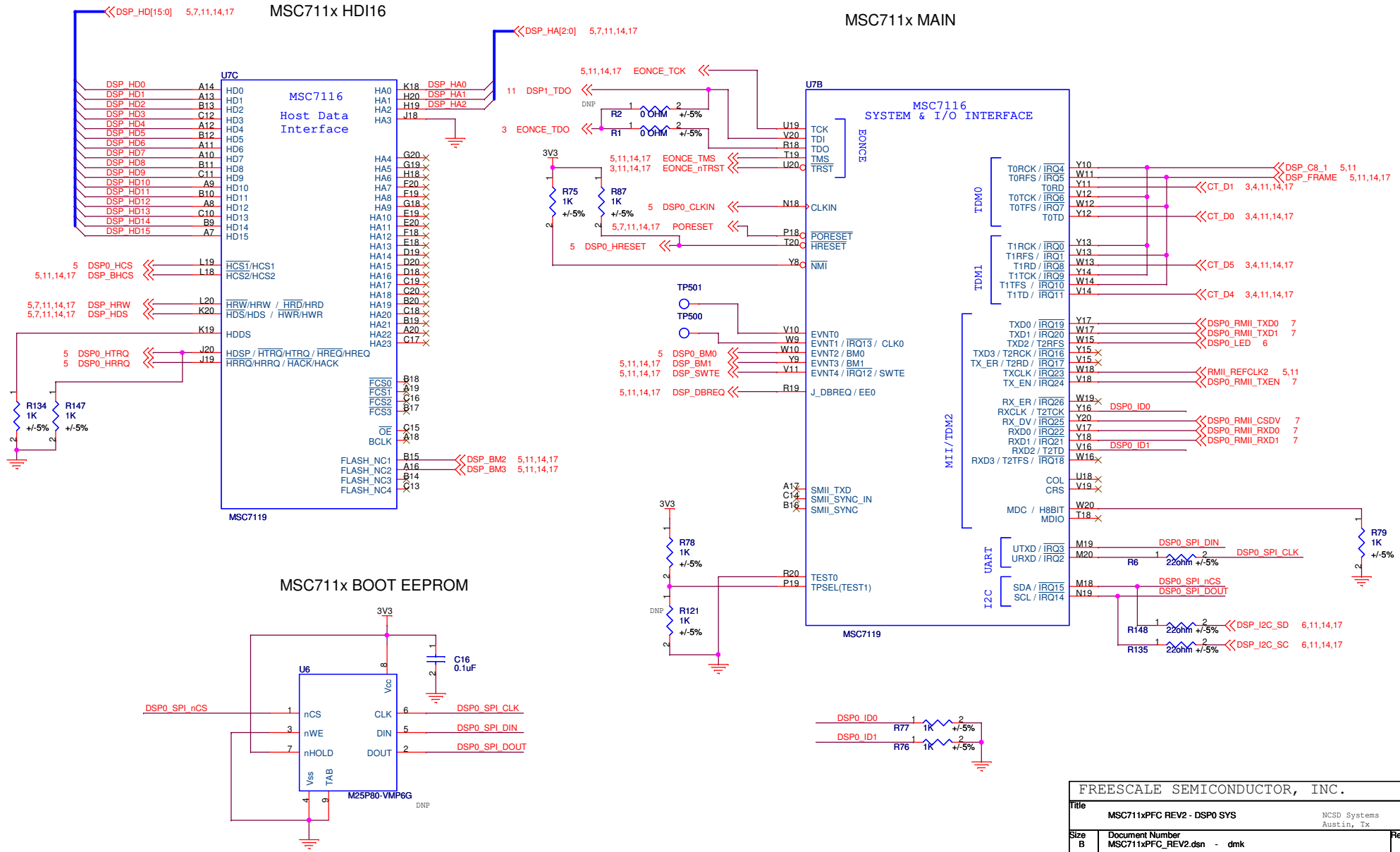


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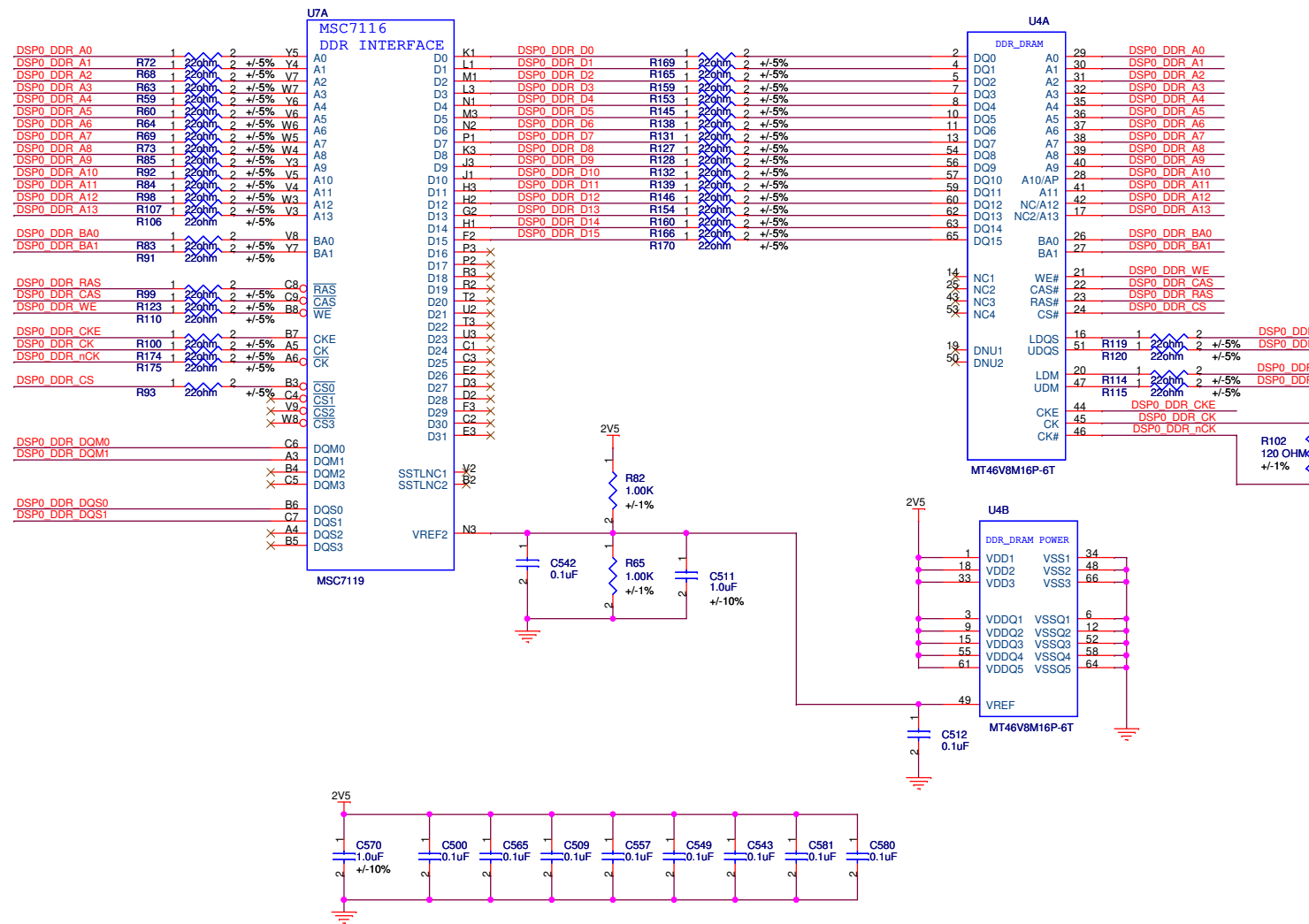
ENET SWITCH CONFIG

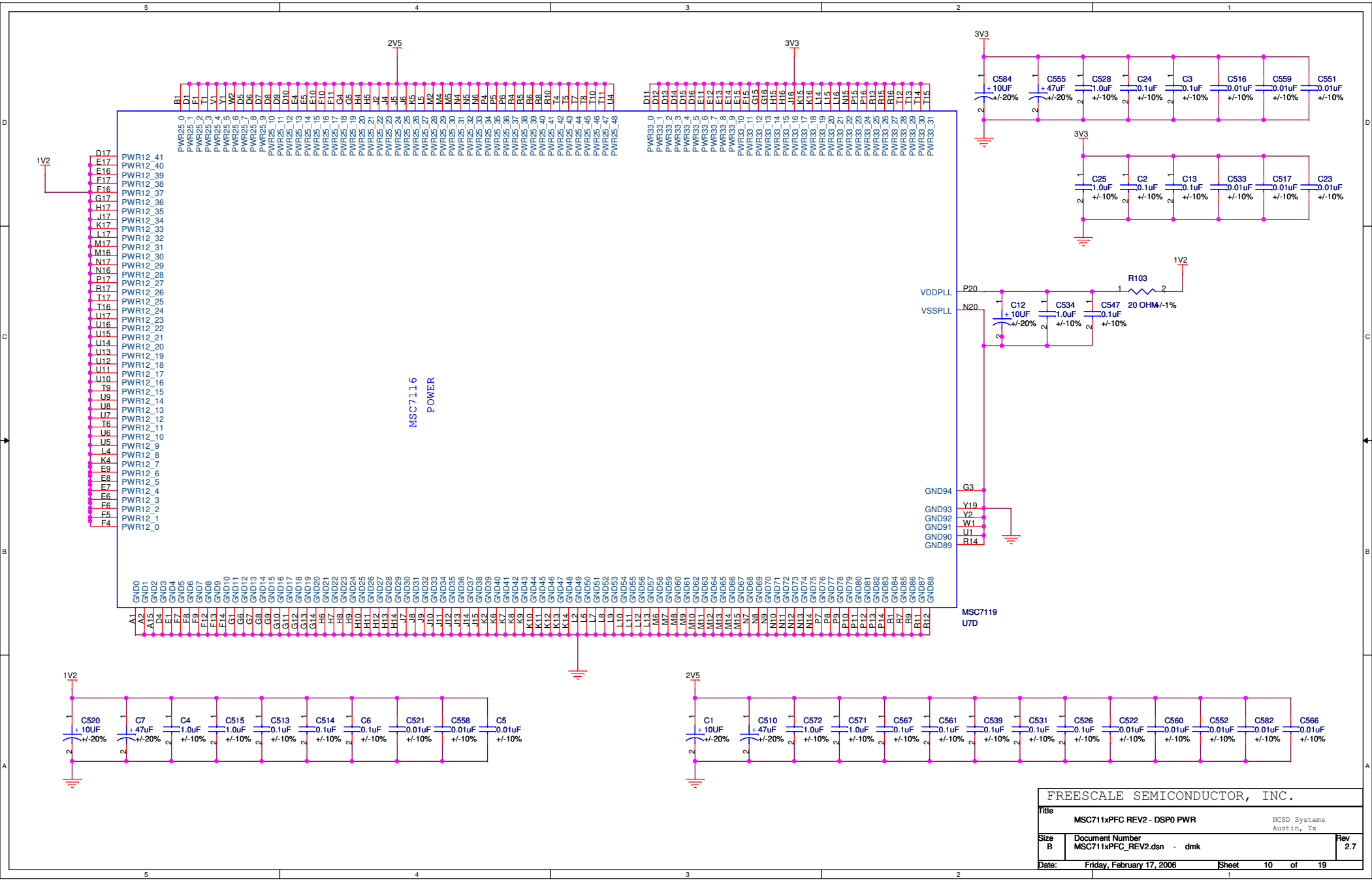


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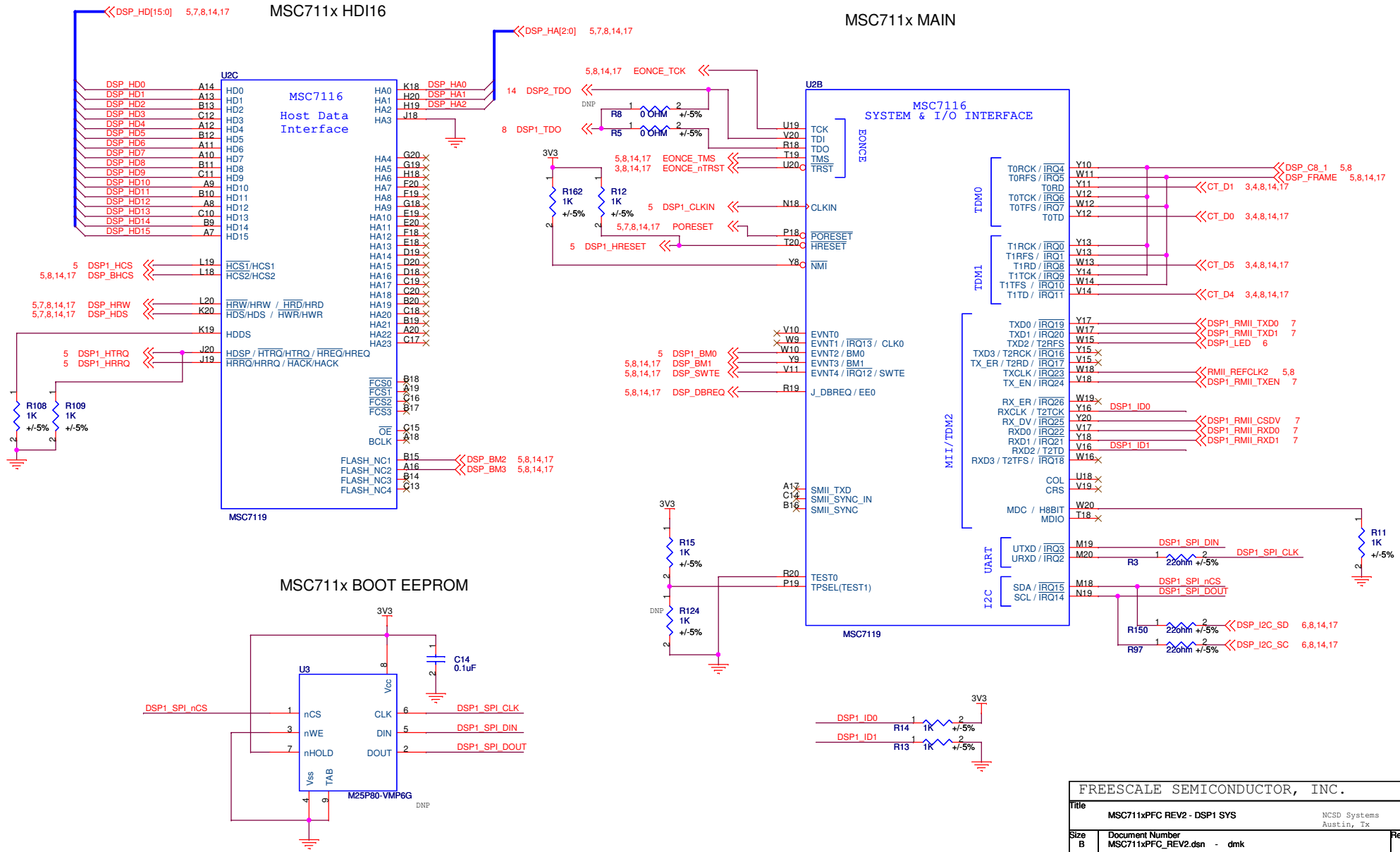


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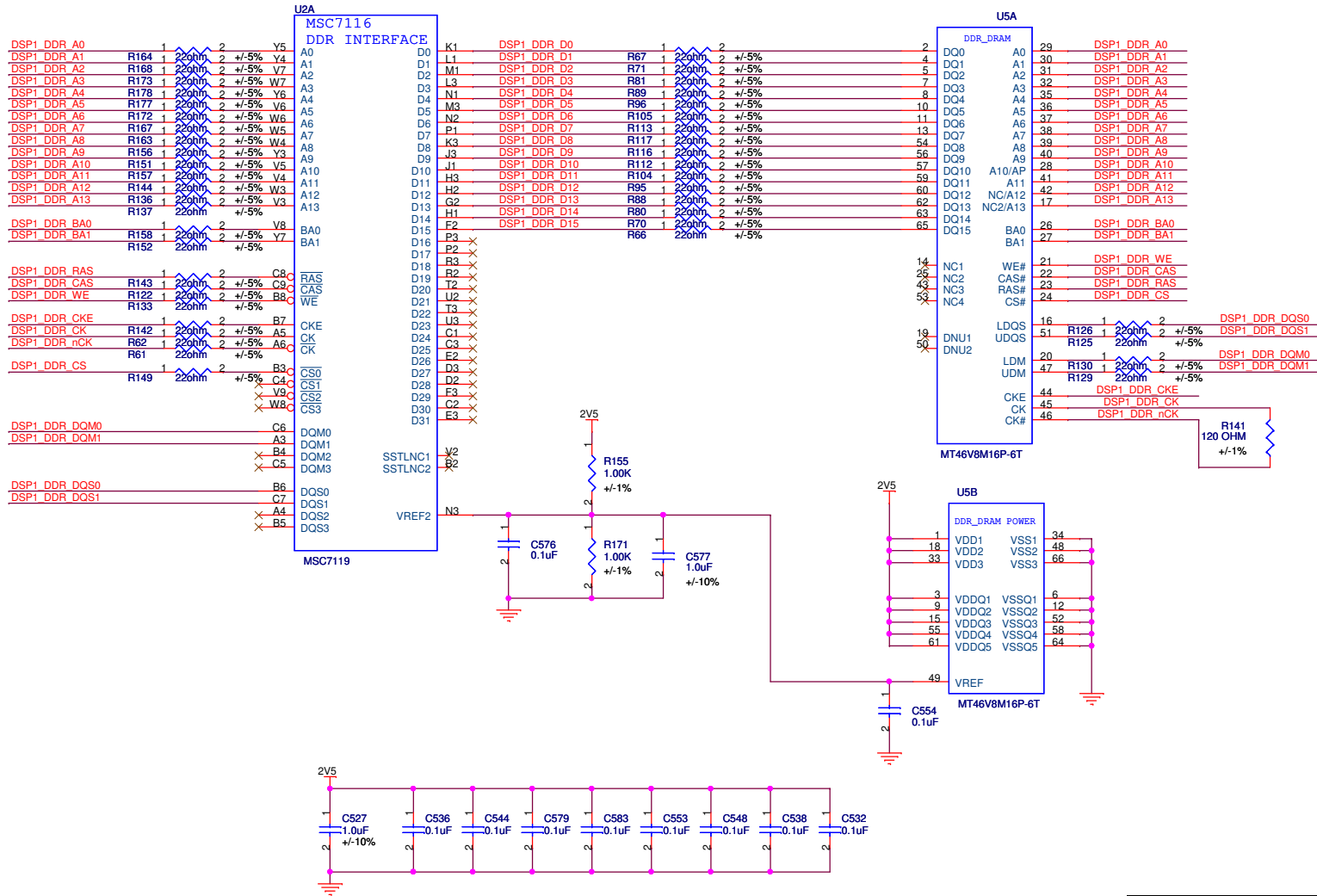


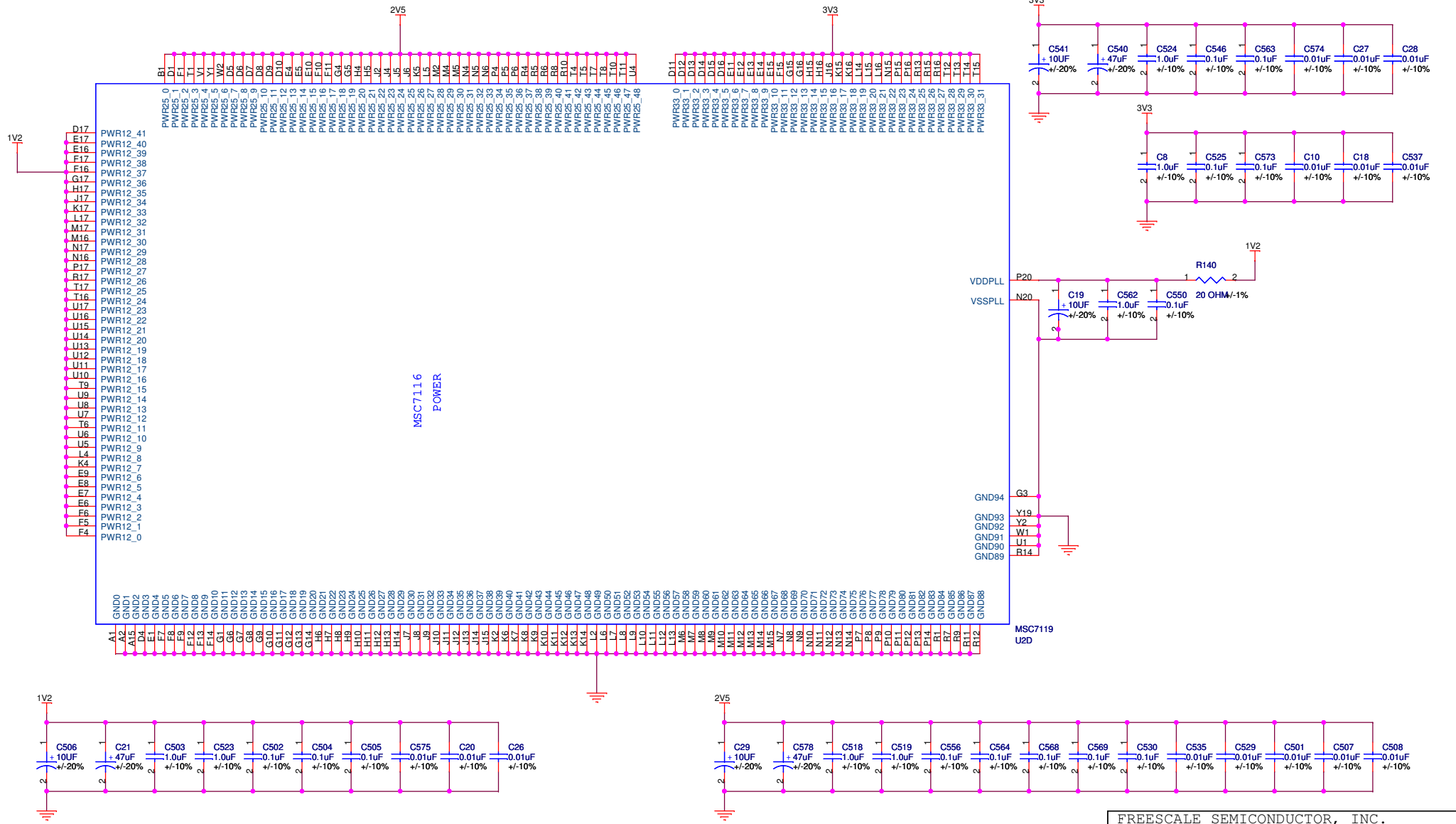


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MSC711x HDI16

MSC7116
Host Data Interface

MSC7119

MSC711x BOOT EEPROM

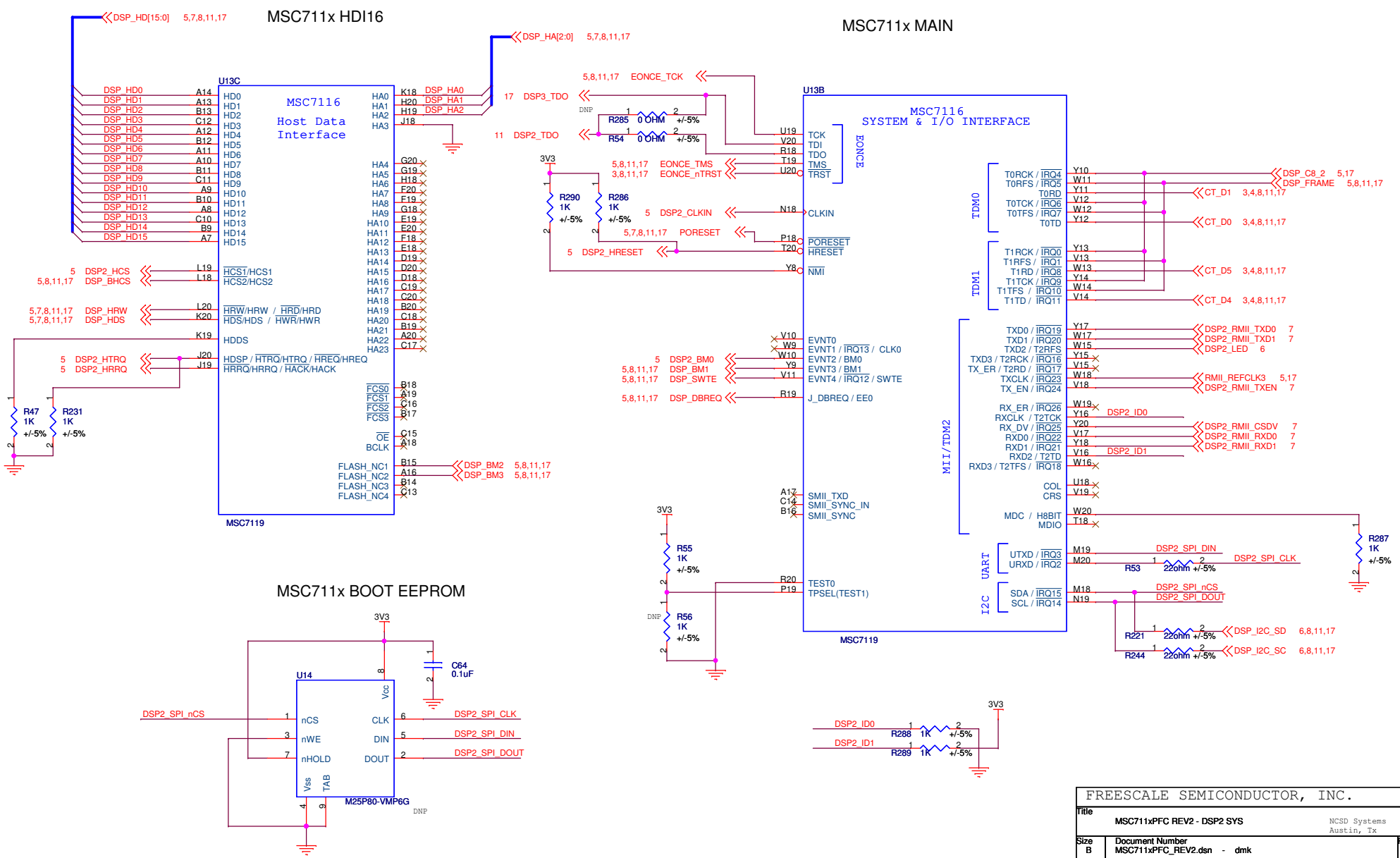
M25P80-VMP6G

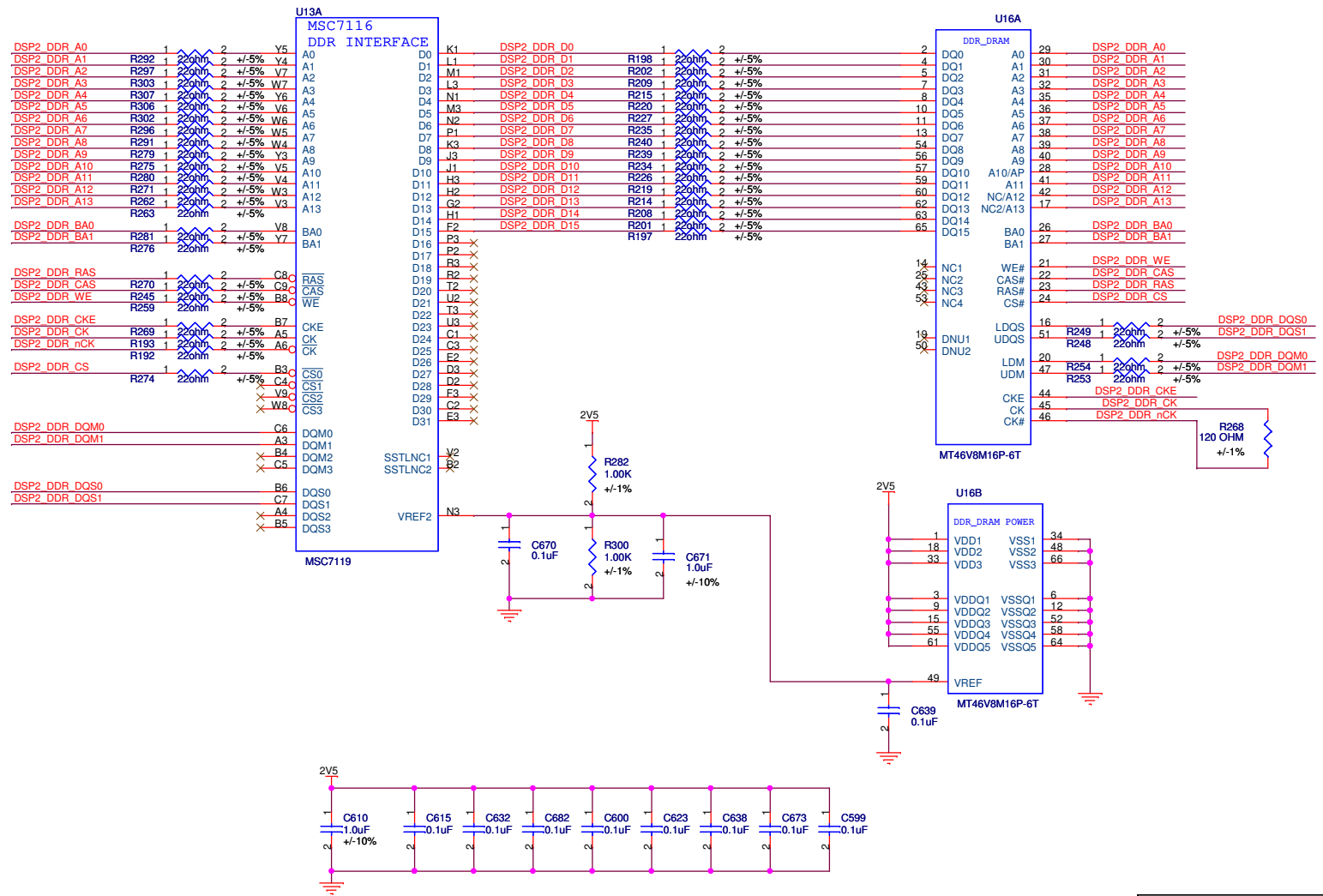
MSC711x MAIN

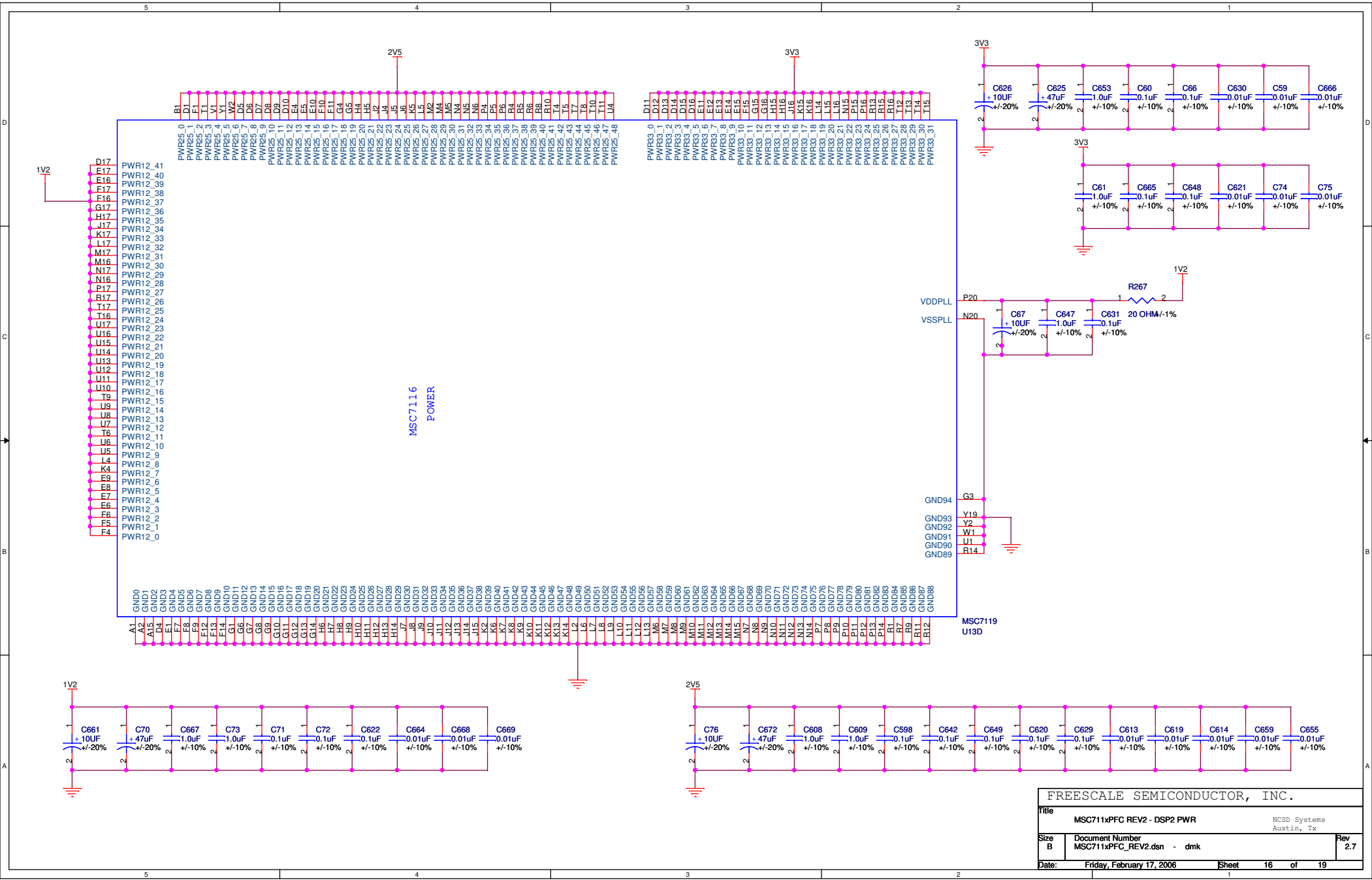
MSC7116
SYSTEM & I/O INTERFACE

MSC7119

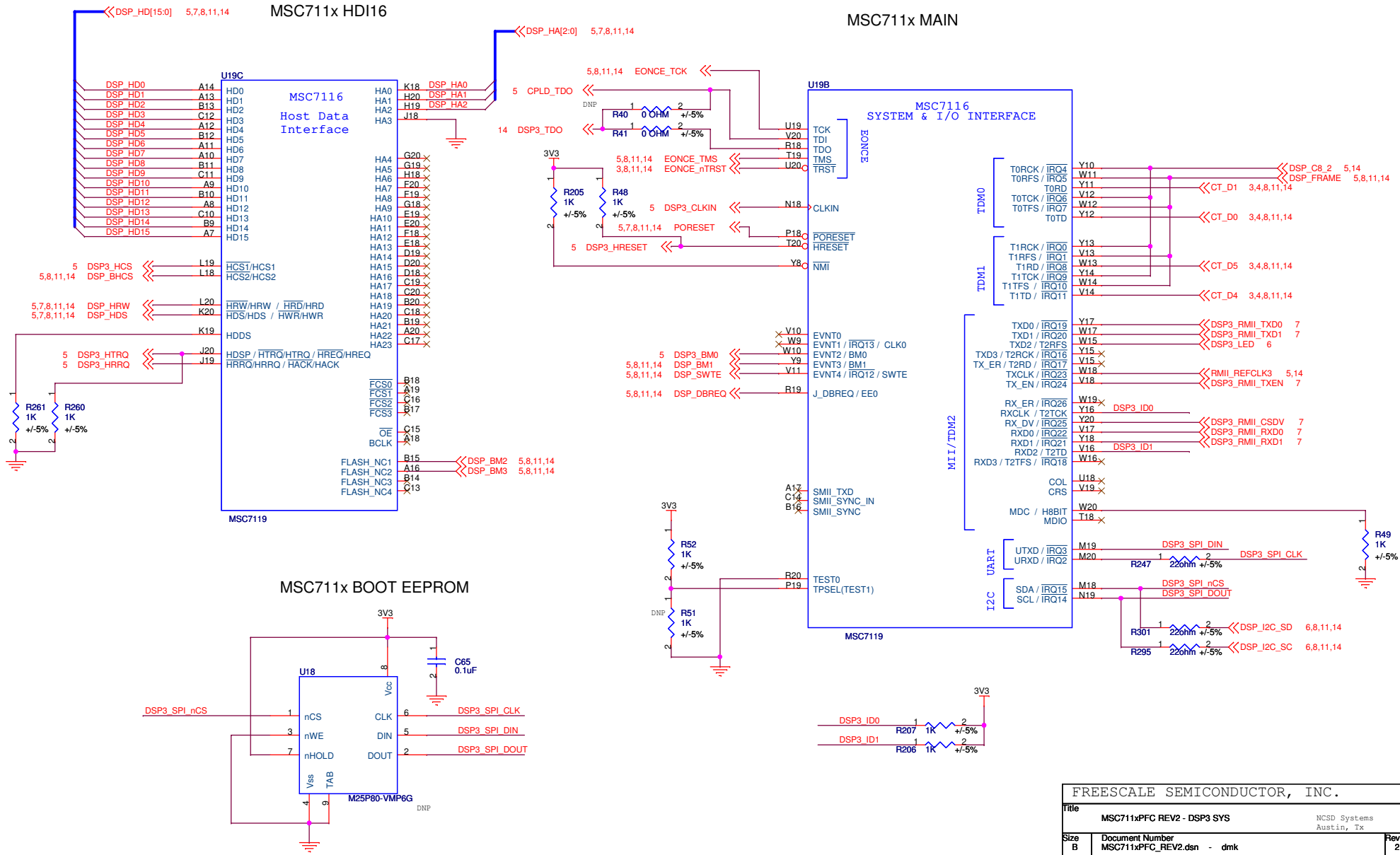
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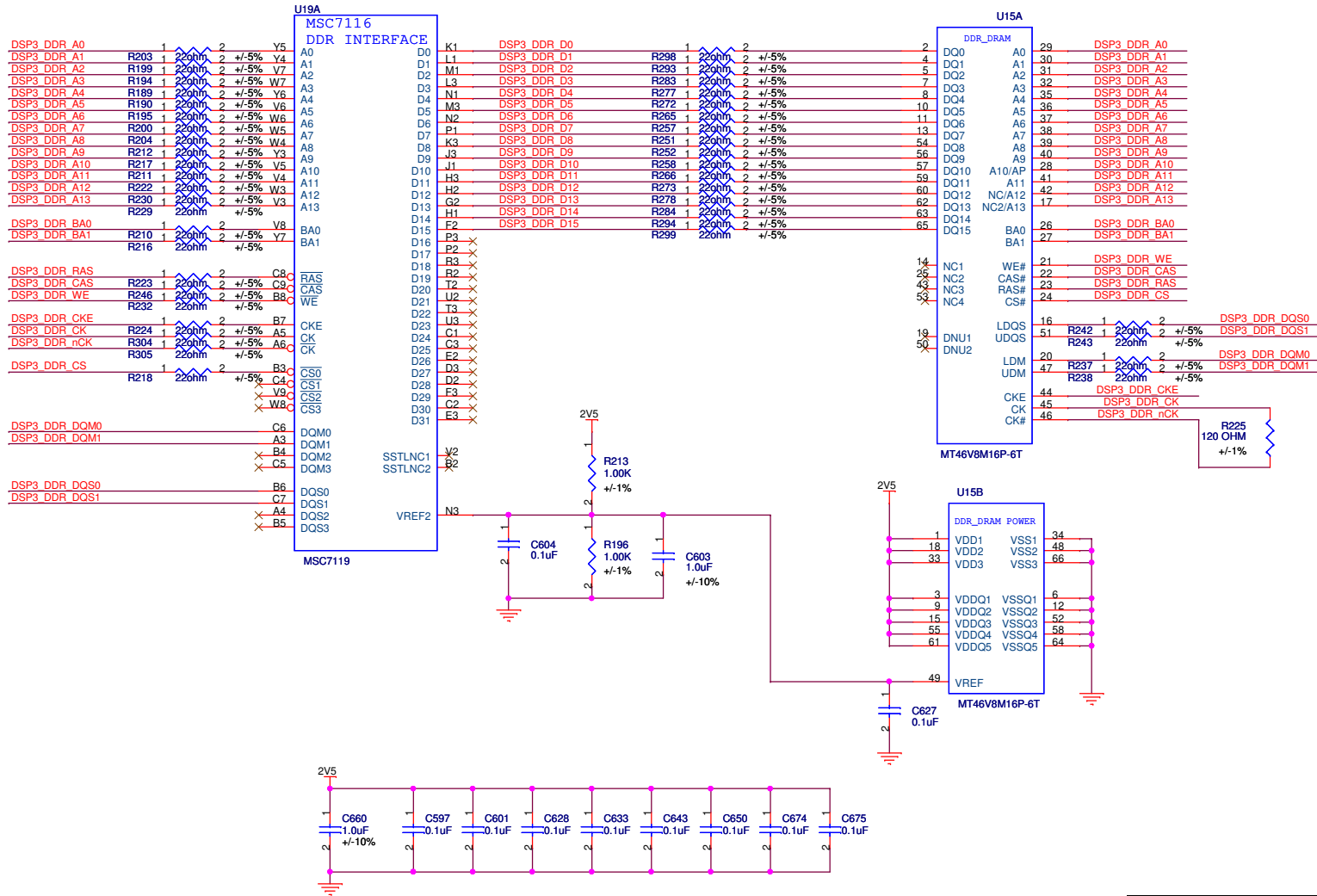


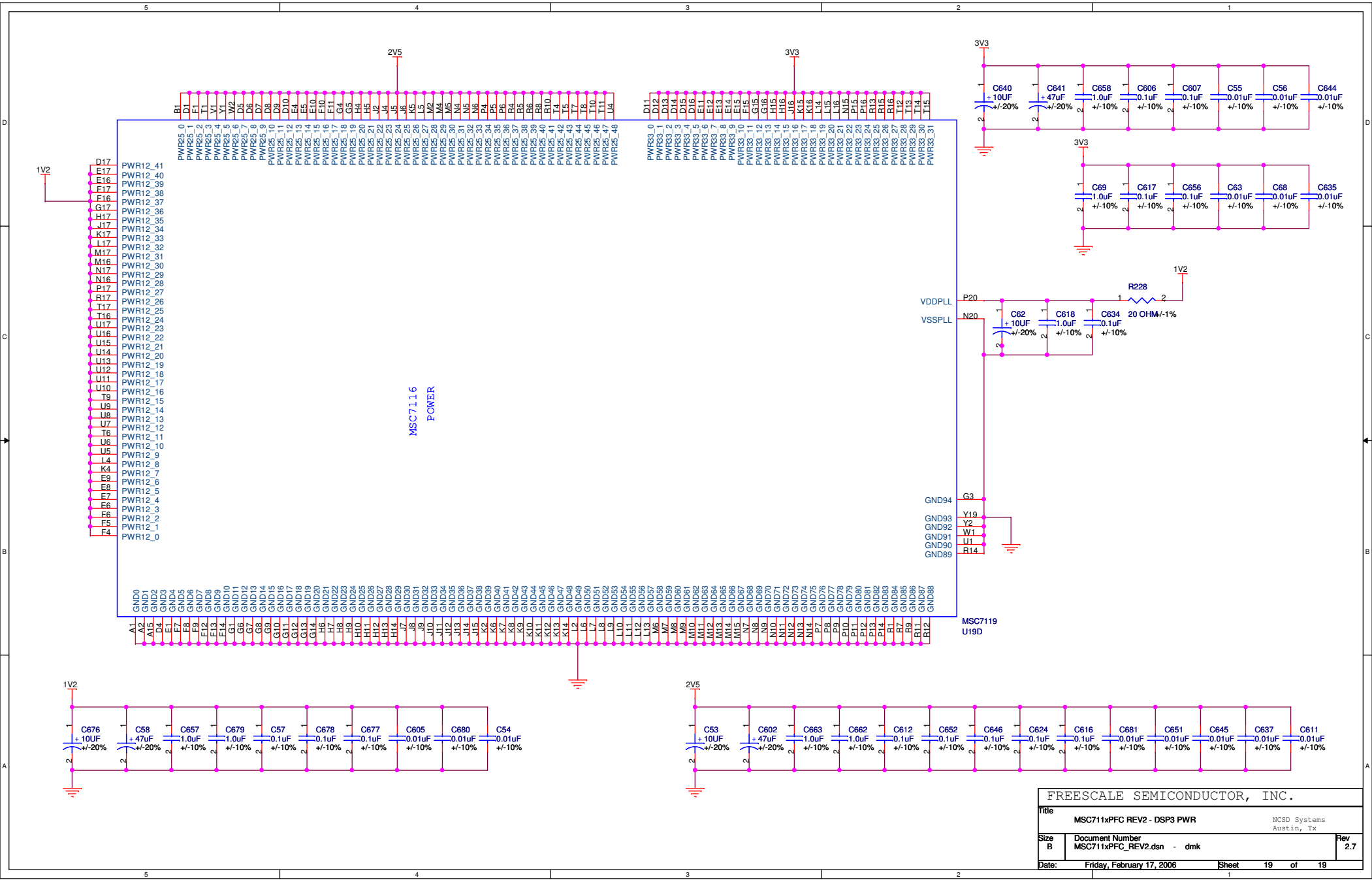


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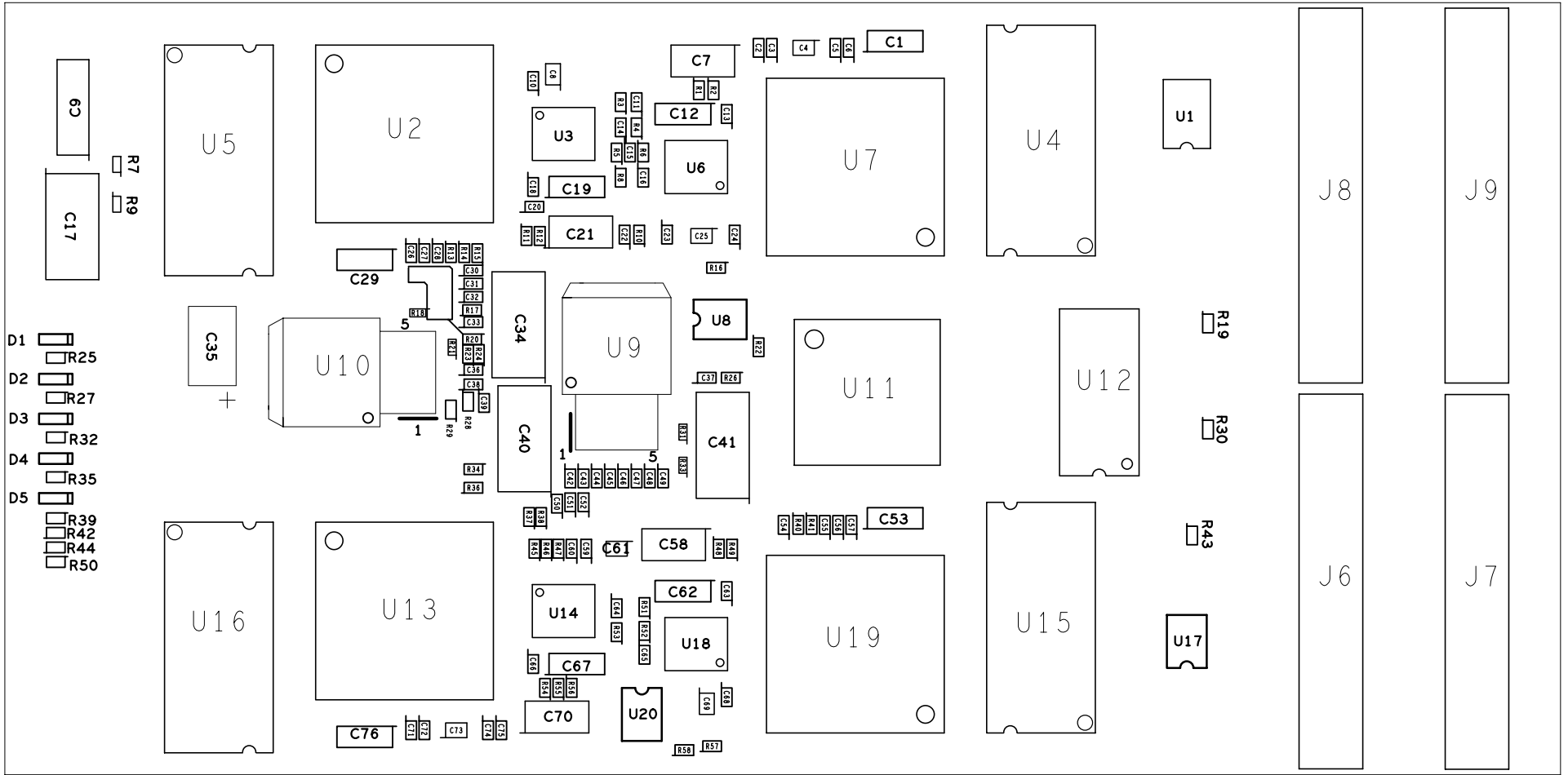
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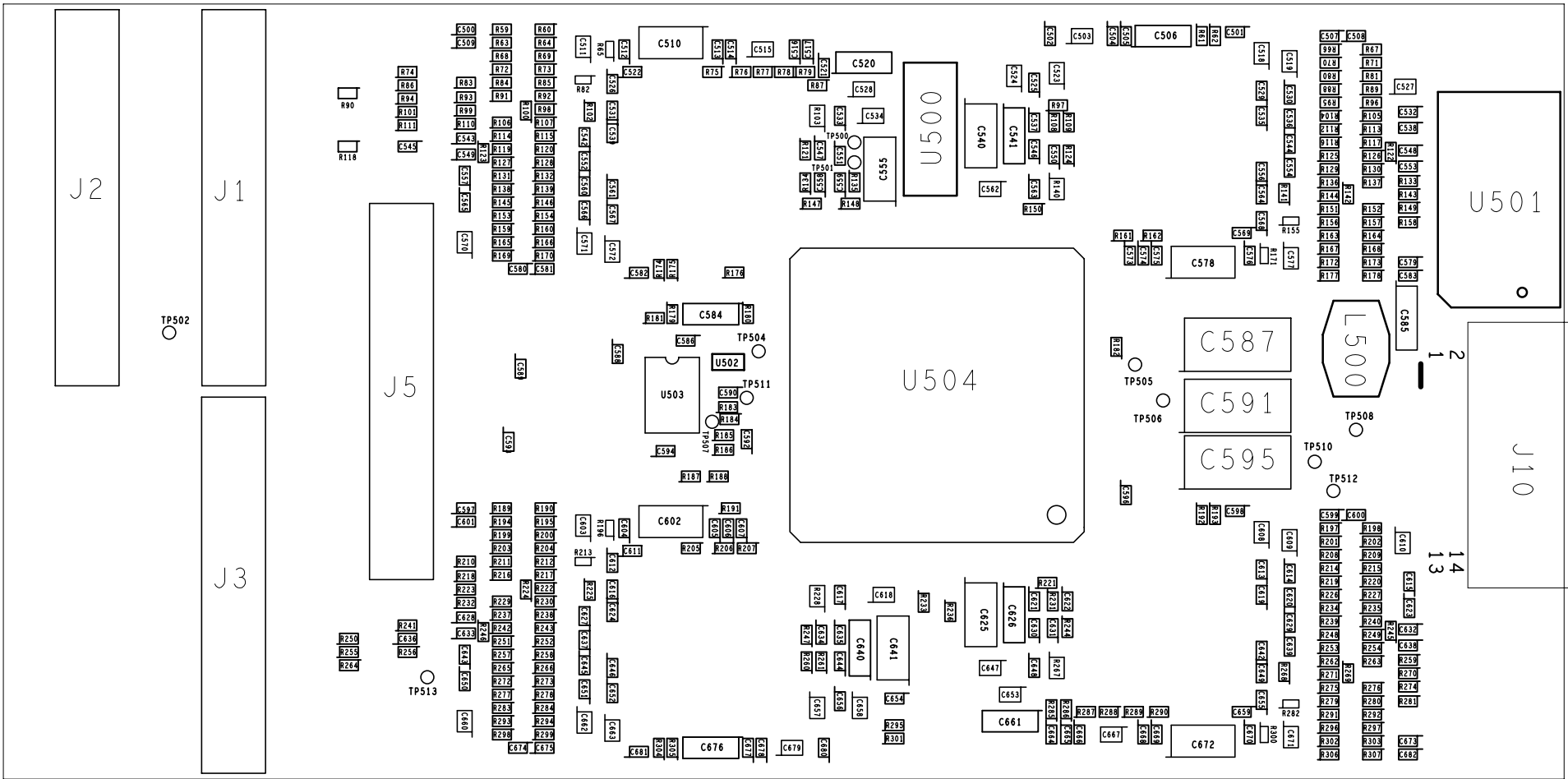




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Appendix C SPT711xPFCE Assembly Drawing





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