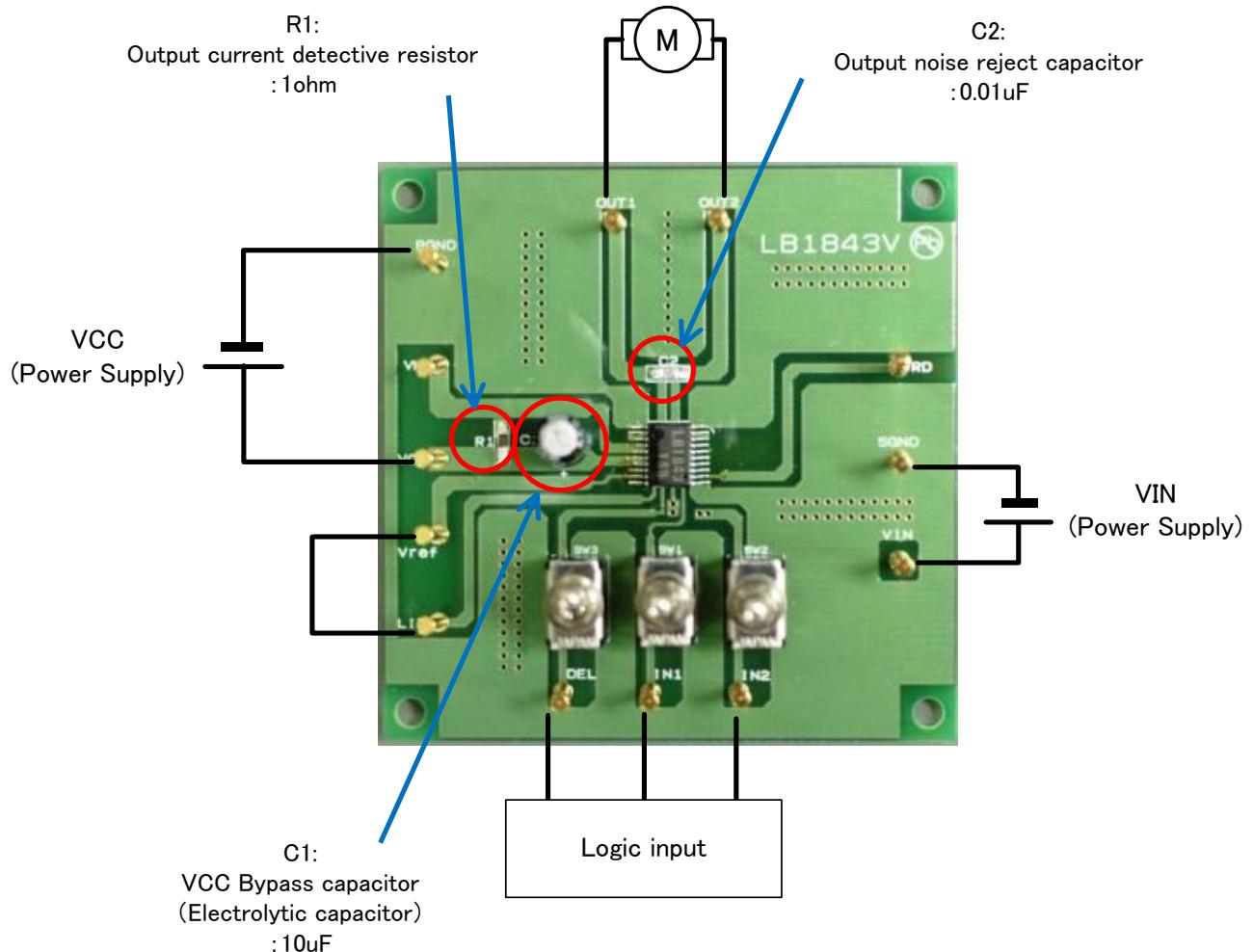


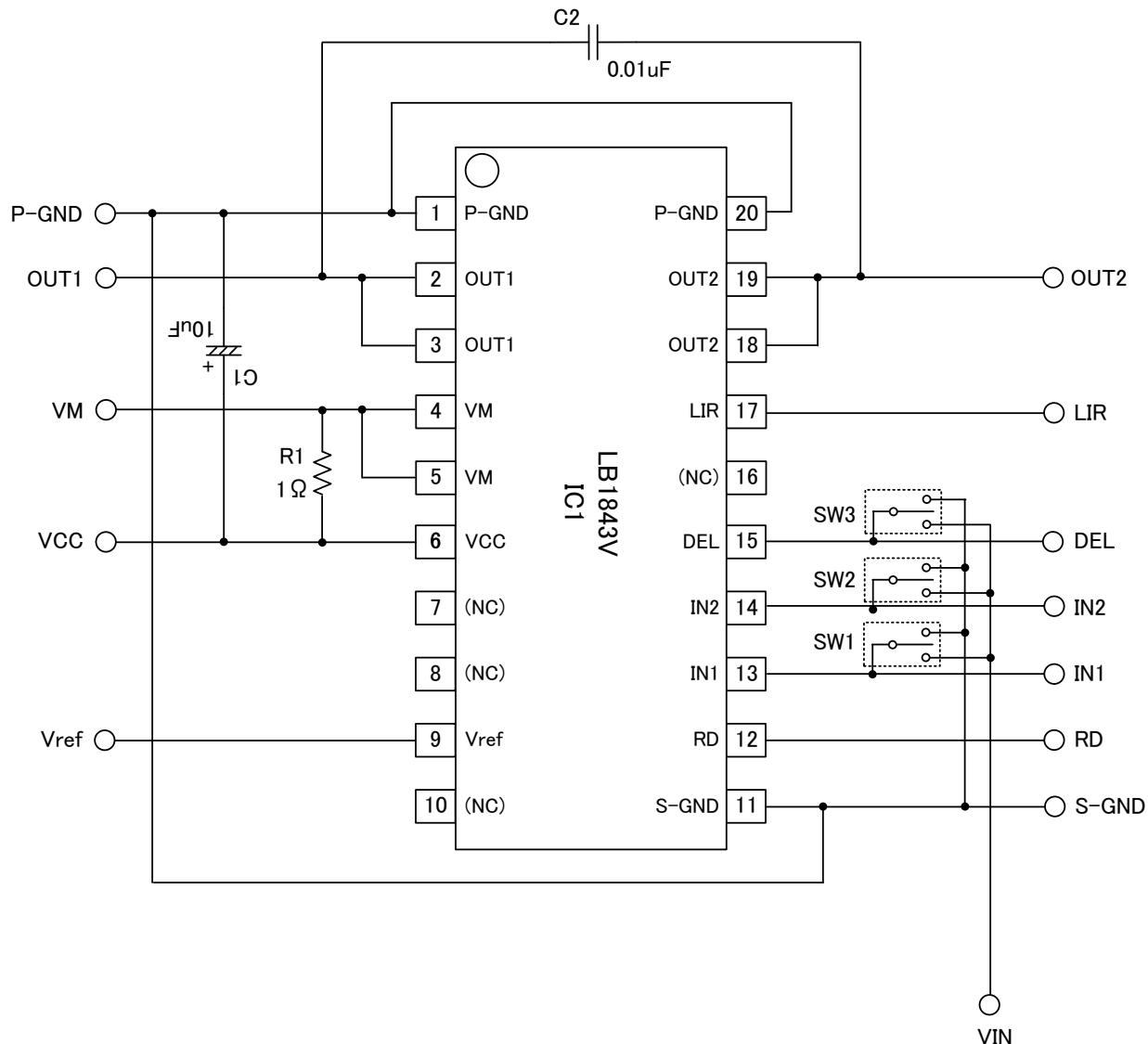
Test Procedure for the LB1843VGEVB Evaluation Board

09/08/2012





(Circuit diagram of the evaluation board)





Evaluation Board Manual

[Supply Voltage]

VCC (3 to 9V): Power Supply for LSI

[Toggle Switch State]

Upper Side: High (VIN)
Middle: Open, enable to external logic input
Lower Side: Low (GND)

[Operation Guide]

For DC motor control

1. **Initial Condition Setting:** Set the toggle switchs “Open or Low”
2. **Motor Connection:** Connect the Motor between OUT1 and OUT2.
3. **Power Supply:** Supply DC voltage to VCC, VIN.
4. **Motor Operation:** Set DEL, IN1 and IN2 terminals according to the purpose (See LB1843V datasheet).

Truth Table

Input		Output		Mode
IN1	IN2	OUT1	OUT2	
L	L	Off	Off	Standby
H	L	H	L	Forward
L	H	L	H	Reverse
H	H	L	L	Brake

Output Current Limitation and Detector Output

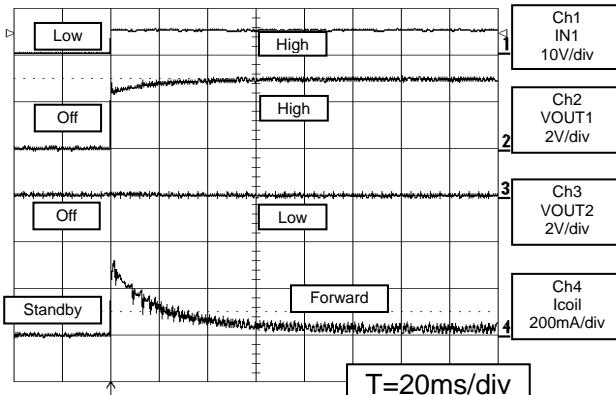
DEL	OUT output	RD
H	Limit	L
	Non-limit	Off
L	Saturated	Off

DC motor load

VCC=3V, IN2=”L”

Current waveform example

“motor start”

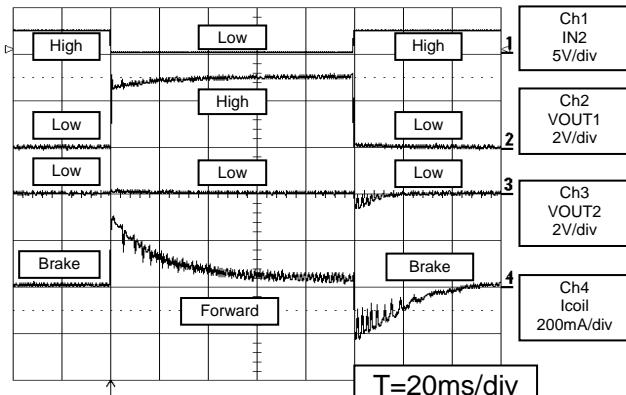


DC motor load

VCC=3V, IN1=”H”

Current waveform example

“Forward current” and “Brake current”



Sample application timing chart

- 1) Connect a DC motor ($RL = R$) between OUT1 and OUT2, and with the RD pin pulled up, input a forward rotation signal ($IN1 = \text{high}$, $IN2 = \text{low}$).
Because the output is used in the saturated state at startup, set the DEL input to low.
- 2) The DC motor starts up, and the startup current ($IST = VM/R$) flows to the motor.
- 3) The DC motor rotates in the normal state. At this point, set the DEL input to high.
- 4) If the DC motor locks, the motor current IM increases to the point of $Ilimit (= VLIR/(10Rf))$, the output current limiter operates to limit the output current. At the same time, RD is output low from the set current detection circuit.

